PISO-P32C32/P32A32/P64/C64/A64

User's Manual

Warranty

All products manufactured by ICP DAS are warranted against defective materials for a period of one year from the date of delivery to the original purchaser.

Warning

ICP DAS assumes no liability for damages consequent to the use of this product. ICP DAS reserves the right to change this manual at any time without notice. The information furnished by ICP DAS is believed to be accurate and reliable. However, no responsibility is assumed by ICP DAS for its use, not for any infringements of patents or other rights of third parties resulting from its use.

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1. Introduction

The PISO-P32C32 consists of 32 channels of isolated D/I & 32 channels of isolated D/O (**Current Sinking**). The PISO-P32A32 consists of 32 channels of isolated D/I & 32 channels of isolated D/O (**Current Sourcing**). The PISO-P64 consists of 64 channels of isolated D/I. The PISO-C64 consists of 64 channels of isolated D/O (**Current Sinking**). The PISO-A64 consists of 64 channels of isolated D/O (**Current Sourcing**). The D/I specifications of PISO-P32C32, PISO-P64 & PISO-P32A32 are the same.

1.1 Specifications

Isolated digital input

- Input voltage: 5V to 30V
- Input impedance: 3K
- Isolation voltage
  Using internal power: 3000V
  Using external power: 3750V
- Response time: 30K Hz max.

Isolated digital output

- Isolation voltage: 3750V
- Open collector output: 100 mA/30V per channel
- Response time: 4K Hz typical

I/O channels

	D/I channels	D/O channels
PISO-P32C32	32	32
PISO-P32A32	32	32
PISO-P64	64	0
PISO-C64	0	64
PISO-A64	0	64

Other specifications

- PC compatible PCI bus
- Four isolated I/O banks
- Operating Temperature: 0°C to 60°C
- Storage Temperature: -20°C to 80°C
- Humidity: 0 to 90% non-condensing
- Dimensions
  PISO-P32C32/P32A32: 180mm X 105mm
  PISO-P64 : 180mm X 105mm
  PISO-C64/A64 : 180mm X 105mm
- Power Consumption
  PISO-P32C32/P32A32: +5V @ 600mA (typical)
  PISO-P64: +5V @ 400mA (typical)
  PISO-C64/A64: +5V @ 800mA (typical)

1.2 Order Description

- PISO-P32C32: PCI bus with 32-bit D/I, 32-bit D/O **(Current Sinking)**.
- PISO-P32A32: PCI bus with 32-bit D/I, 32-bit D/O **(Current Sourcing)**.
- PISO-P64: PCI bus, 64-bit D/I.
- PISO-C64: PCI bus, 64-bit D/O **(Current Sinking)**.
- PISO-A64: PCI bus, 64-bit D/O **(Current Sourcing)**

1.2.1 Options

- DB-24P, DB-24PD: 24 channel isolated D/I board
- DB-24R, DB-24RD: 24 channel relay board
- DB-24PR, DB-24PRD: 24 channel power relay board
- DB-16P8R: 16 channel isolated D/I and 8 channel relay output board
- DB-24POR: 24 channel Photo MOS output board
- DB-24SSR: 24 channel Solid State output board
- DB-24C: 24 channel open-collector output board
- ADP-37/PCI: extender, 50-pin OPTO-22 header to DB-37 for PCI Bus I/O boards
- ADP-50/PCI: extender, 50-pin OPTO-22 header to 50-pin header, for PCI Bus I/O boards

1.3 PCI Data Acquisition Family

We provide a family of PCI-BUS data acquisition cards. These cards can be divided into three groups as follows:

1. **PCI-series: first generation, isolated or non-isolated cards**
   PCI-1002/1202/1800/1802/1602: multi-function family, non-isolated
   PCI-P16R16/P16C16/P16POR16/P8R8: D/I/O family, isolated
   PCI-TMC12: timer/counter card, non-isolated
2. **PIO-series: cost-effective generation, non-isolated cards**
   PIO-823/821: multi-function family
   PIO-D168/D144/D96/D64/D56/D48/D24: D/I/O family
   PIO-DA16/DA8/DA4: D/A family
3. **PISO-series: cost-effective generation, isolated cards**
   PISO-813: A/D card
   PISO-P32C32/P32A32/P64/C64/A64: D/I/O family
   PISO-P8R8/P8SSR8AC/P8SSR8DC: D/I/O family
   PISO-730/730A: D/I/O card
   PISO-DA2: Channel to Channel Isolated D/A card

1.4 Product Checklist

In addition to this manual, the package includes the following items:

- One PISO-P32C32/P32A32/P64/C64/A64 card.
- One driver diskette or CD-ROM.
- One release note.

It's recommended to read the release note first. All-important information will be given in the release note. It tells:

1. Where you can find the software driver & utility.
2. How to install software & utility.
3. Where is the diagnostic program?
4. FAQ.

Attention!

If any of these items are missing or damaged, contact the dealer from whom you purchased the product. Please save the shipping materials and carton in case you want to ship or store the product in the future.

2. Hardware configuration

2.1 Board Layout

The board layout of PISO-P32C32/P32A32 is as follows:

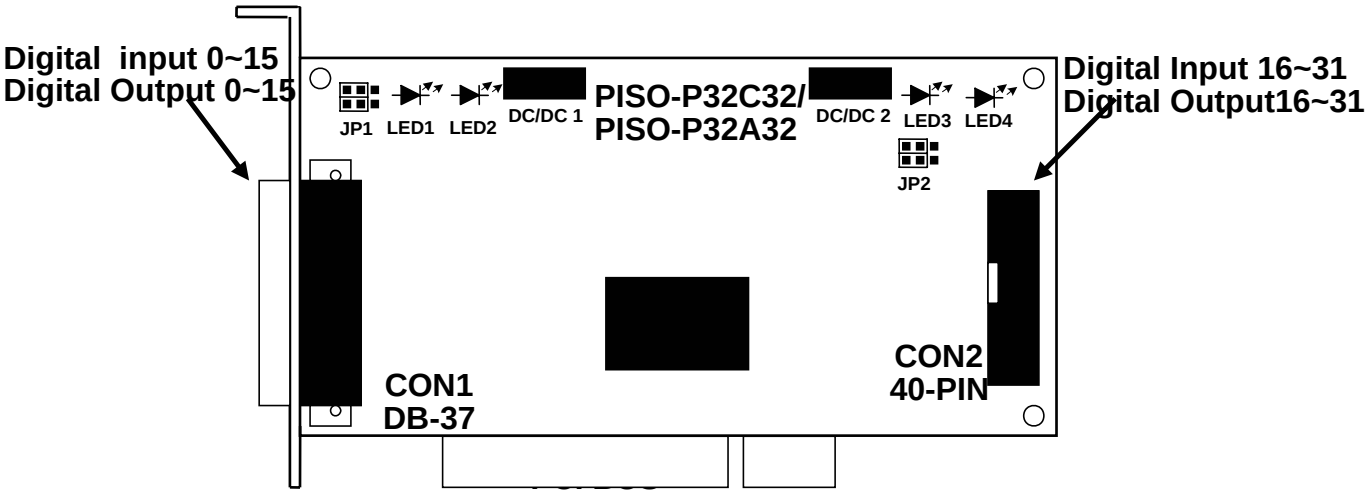


Figure 2-1A. Board layout of PISO-P32C32/P32A32

JP1/JP2	INTERNAL	EXTERNAL
	Default settling	

LED1: Power indicator for DO_0 to DO_15
LED2: Power indicator for DI_0 to DI_15
LED3: Power indicator for DO_16 to DO_31
LED4: Power indicator for DI_16 to DI_31
JP1: Select internal/external power for DI_0 to DI_15 (3000V isolation)
JP2: Select internal/external power for DI_16 to DI_31 (3000V isolation)

Isolation bank 1: DI_0 to DI_15, Power=CON1_18, Ground=CON1_19
Isolation bank 2: DO_0 to DO_15, Power=CON1_37, Ground=CON1_1 & CON1_20
Isolation bank 3: DI_16 to DI_31, Power=CON2_18, Ground=CON2_19
Isolation bank 4: DO_16 to DO_31, Power=CON2_37, Ground=CON2_1 &CON2_20
All four banks are fully isolated from each other.

The board layout of PISO-P64 is as follows:

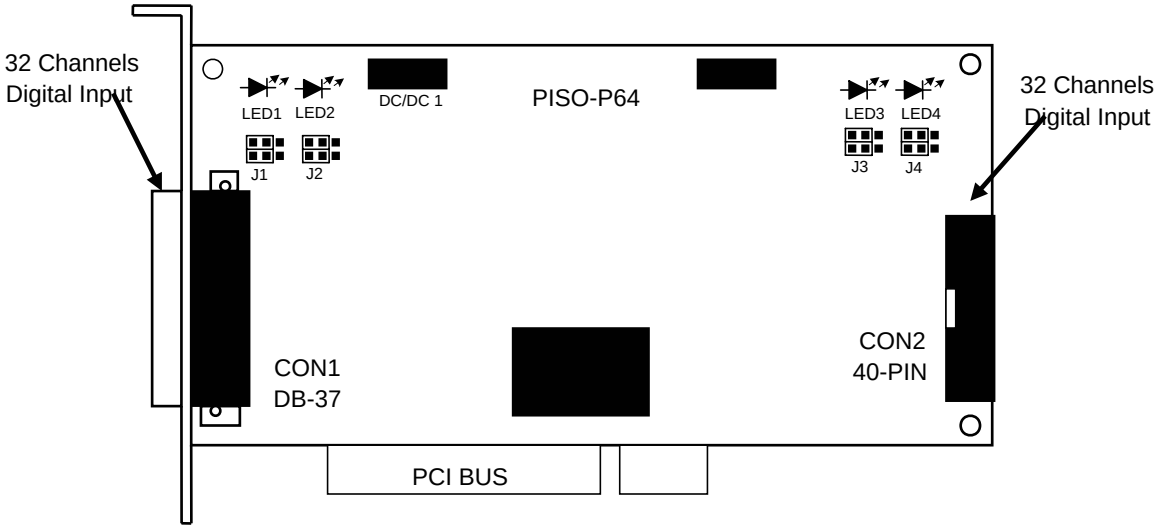


Figure 2-1B. Board layout of PISO-P64

J1/J2/J3/J4	INTERNAL	EXTERNAL
	Default	

LED 1: power indicator for DI_0 to DI_15
LED 2: power indicator for DI_16 to DI_31
LED 3: power indicator for DI_32 to DI_47
LED 4: power indicator for DI_48 to DI_63

J1: select internal/external power for DI_0 to DI_15 (3000V isolation)
J2: select internal/external power for DI_16 to DI_31 (3000V isolation)
J3: select internal/external power for DI_32 to DI_47 (3000V isolation)
J4: select internal/external power for DI_48 to DI_63 (3000V isolation)

Isolation bank 1: DI_0 to DI_15, Power=CON1_18, Ground=CON1_1
Isolation bank 2: DI_16 to DI_31, Power=CON1_37, Ground=CON1_20
Isolation bank 3: DI_32 to DI_47, Power=CON2_18, Ground=CON2_1
Isolation bank 4: DI_48 to DI_63, Power=CON2_37, Ground=CON2_20
All four banks are fully isolated from each other.
The DC/DC1 provides the internal power supply for banks 1 & 2.
The DC/DC2 provides the internal power supply for banks 3 & 4.

The board layout of PISO-C64/A64 is as follows:

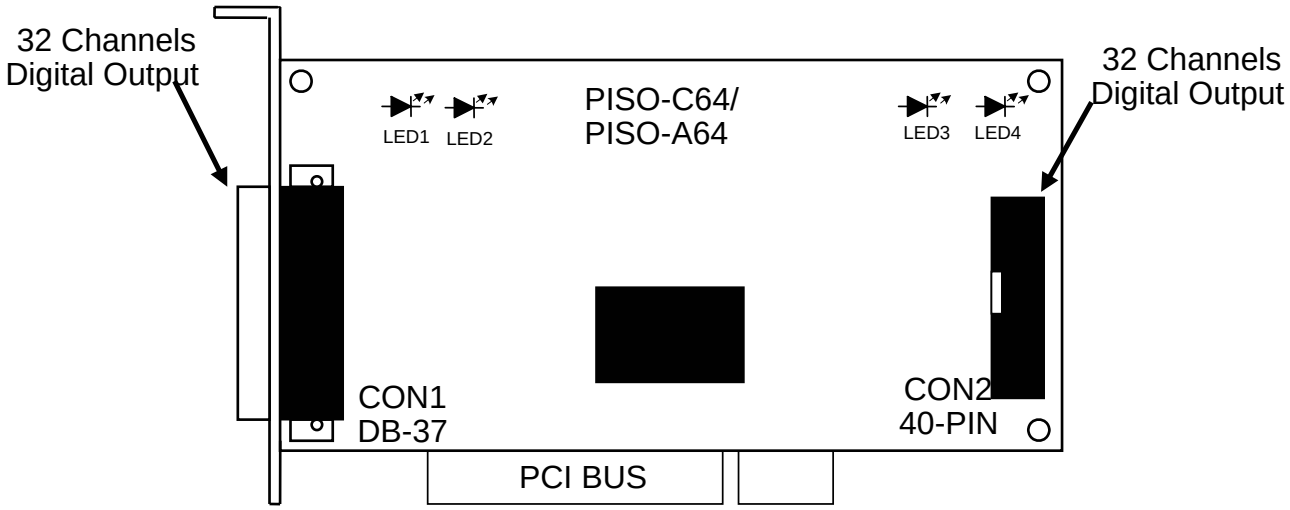


Figure 2-1C. Board layout of PISO-C64/A64

LED 1: power indicator for DO_0 to DO_15
LED 2: power indicator for DO_16 to DO_31
LED 3: power indicator for DO_31 to DO_47
LED 4: power indicator for DO_47 to DO_63

Isolation bank 1: DO_0 to DO_15, Power=CON1_18, Ground=CON1_1
Isolation bank 2: DO_16 to DO_31, Power=CON1_37, Ground=CON1_20
Isolation bank 3: DO_32 to DO_47, Power=CON2_18, Ground=CON2_1
Isolation bank 4: DO_48 to DO_63, Power=CON2_37, Ground=CON2_20

All four banks are fully isolated from each other.

2.2 Isolated D/I Architecture

The D/I architecture of the PISO-P32C32/P32A32 & the PISO-P64 are the same. Select either internal or external power to supply photo-couple digital input power. Here are diagrams for the various configurations:

Configure 1: Internal power supply (Default Setting)

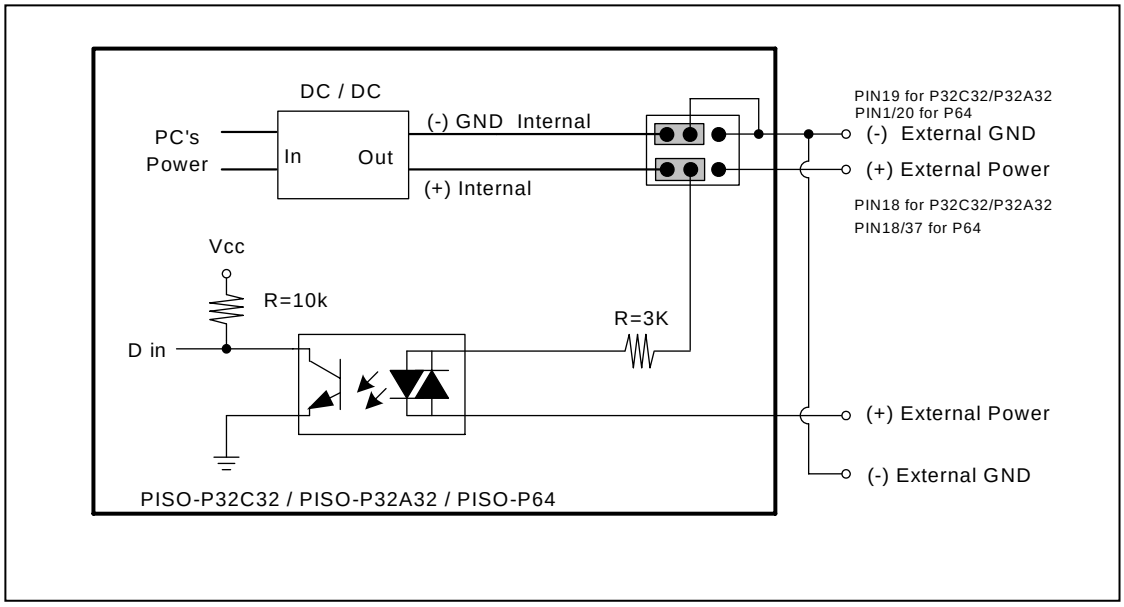


Figure 2-2-1. Isolated D/I Architecture with internal power supply

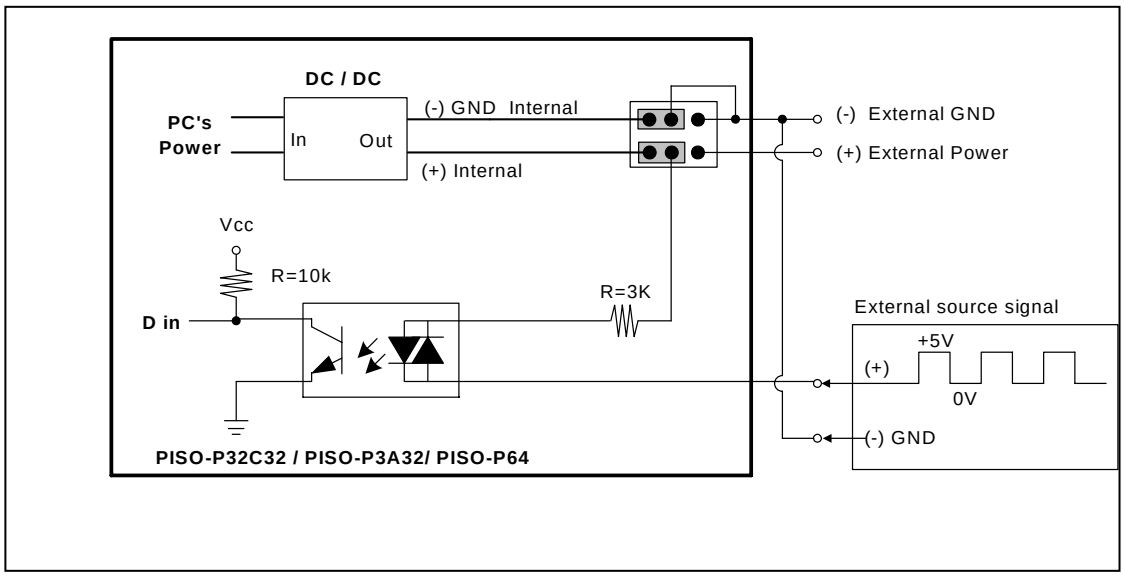


Figure 2-2-2. Typical Applications of D/I with internal power supply

Configure 2: External power supply

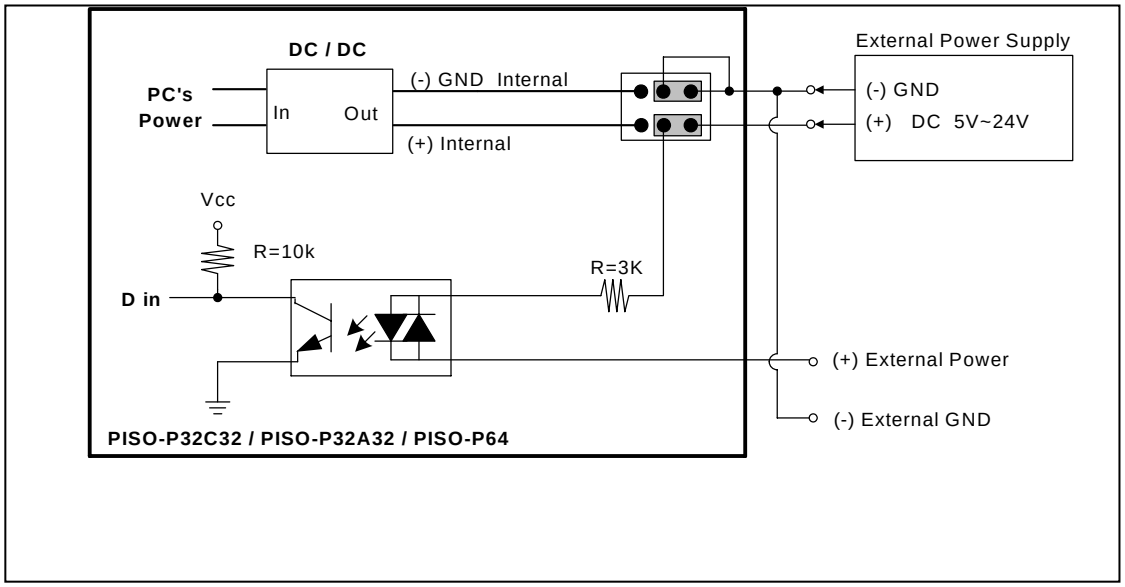


Figure 2-2-3. Isolated D/I Architecture with external power supply

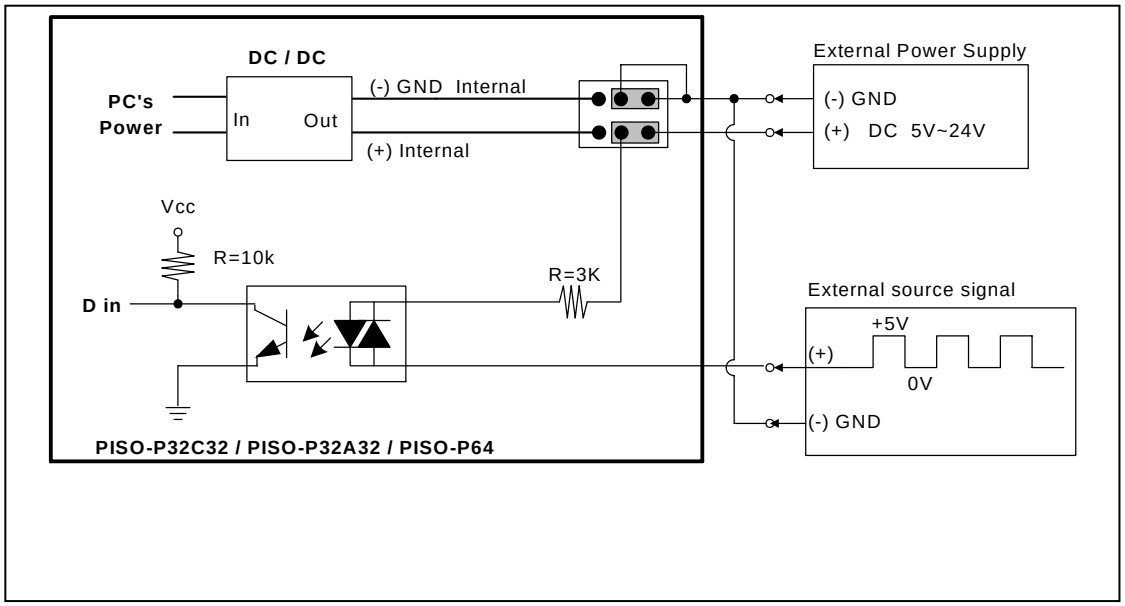


Figure 2-2-4. Typical Applications of D/I with external power supply

2.3 Isolated D/O Architecture

The PISO-P32C32 & the PISO-C64 share the same architecture, and the PISO-P32A32 & the PISO-A64 share the same architecture. Here are block diagrams related to the D/O:

Figure 2-3-1. Isolated D/O Architecture (**Current sinking**)

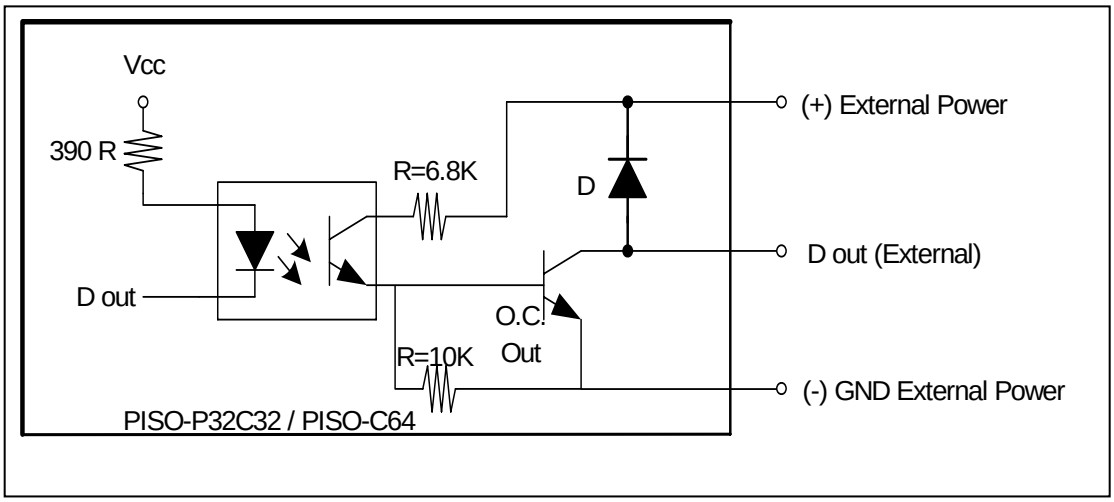


Figure 2-3-2. Typical Applications of D/O (**Current sinking**)

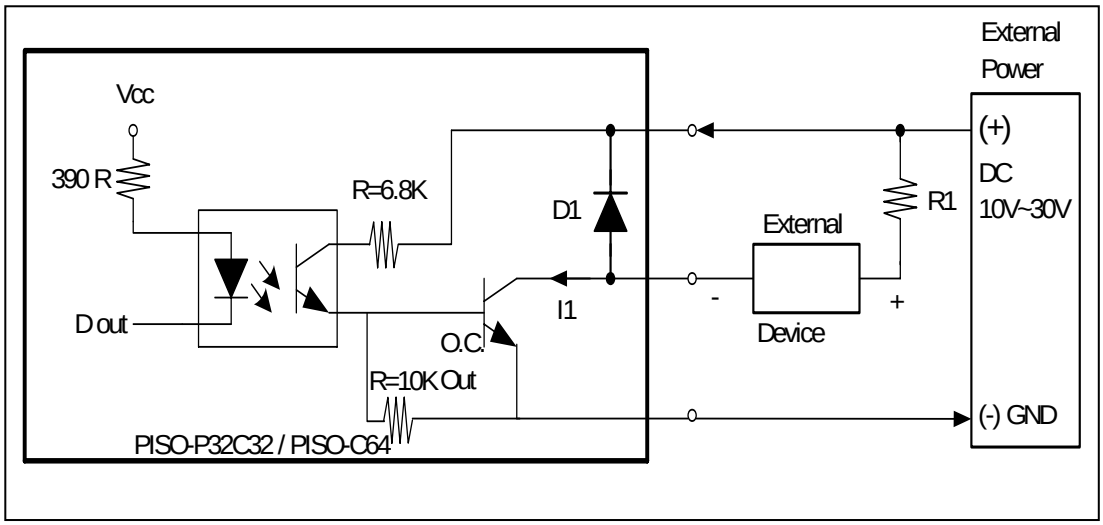


Figure 2-3-3. Isolated D/O Architecture (**Current sourcing**)

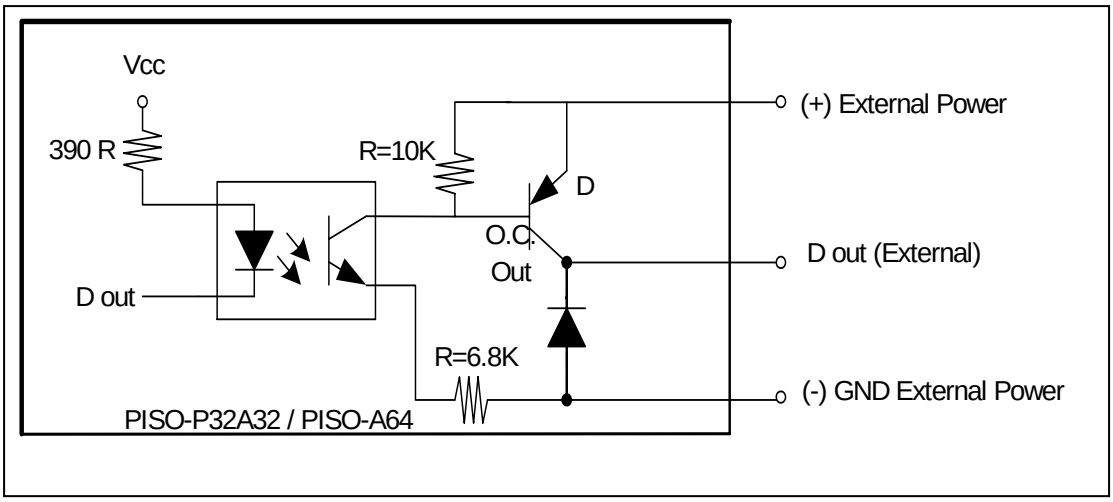
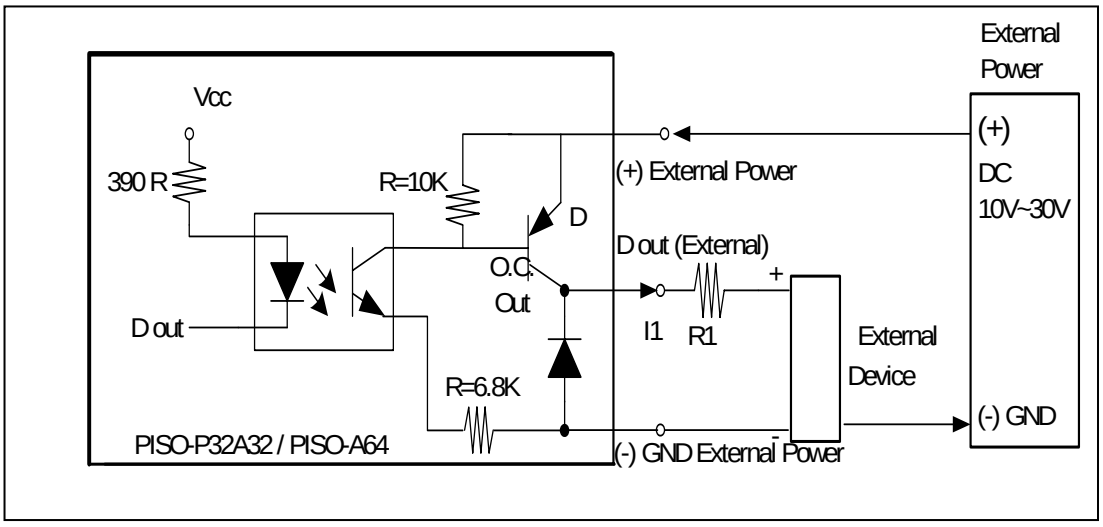


Figure 2-3-4. Typical Applications of D/O (**Current sourcing**)



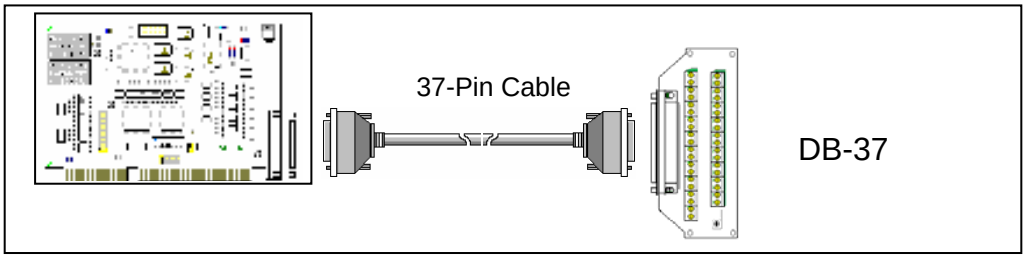
NOTE:

1. The I1, I2, … & I32 must be < 100 mA
2. The R1, R2, ... & R32 are current-limit resistors. They must be designed to let I1, I2, ... & I32 <100 mA.
3. If the internal resistance of the external device is large enough, the R can be omitted.
4. D1, D2, ... & D31 are common-cathode diodes for switching inductive loads. They can be used as relay drivers, hammer drivers, lamp drivers, display drivers, line drivers & logic buffers.

2.4 Daughter Boards

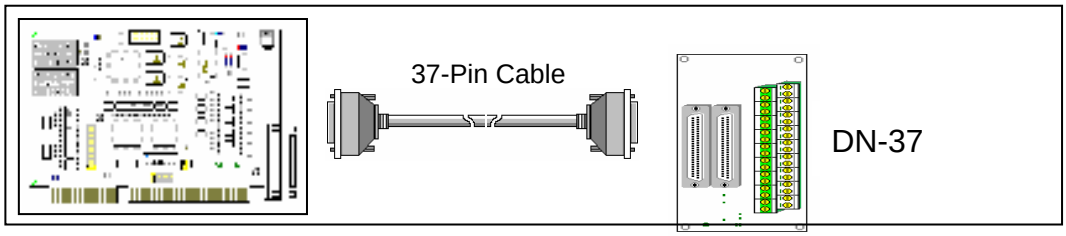
2.4.1 DB-37

The DB-37 is a general-purpose daughter board for D-sub 37 pins. It is designed for easy wiring connections.



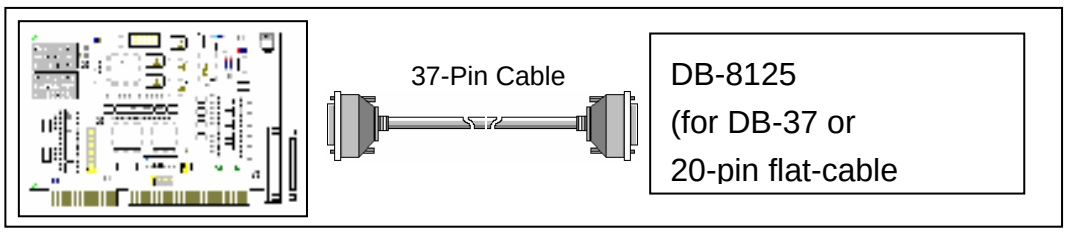
2.4.2 DN-37

The DN-37 is a general-purpose daughter board for DB-37 with DIN-Rail Mounting. It is designed for easy wiring connections.

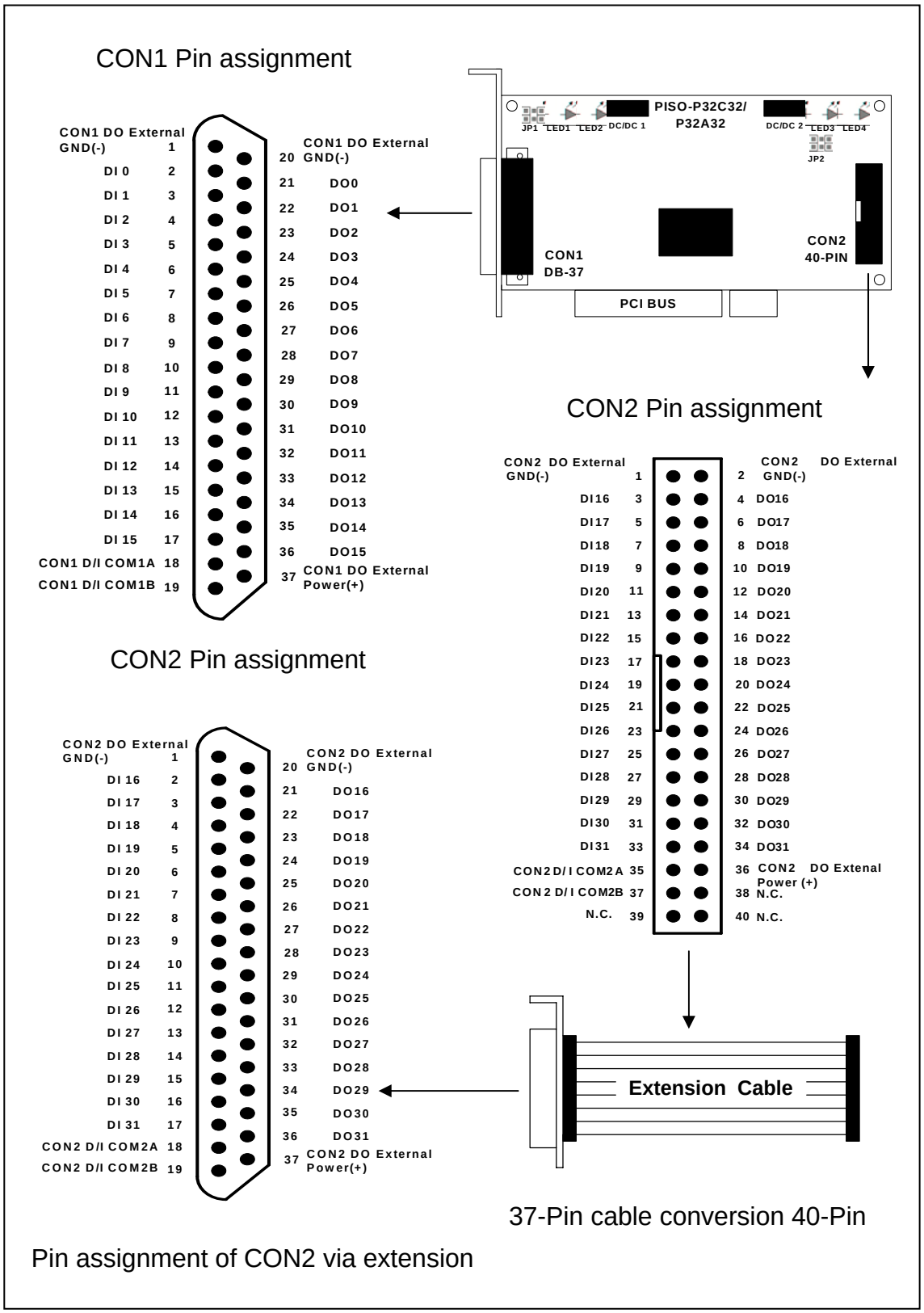


2.4.3 DB-8125

The DB-8125 is a general-purpose screw terminal board. It is designed for easy wiring connection. One DB-37 & two 20-pin flat-cable headers are used in the DB-8125.

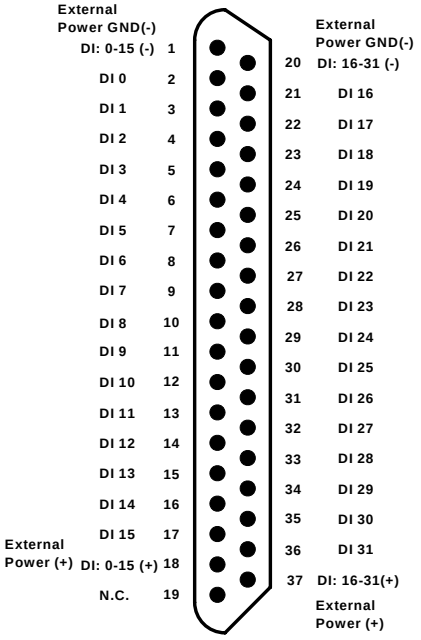


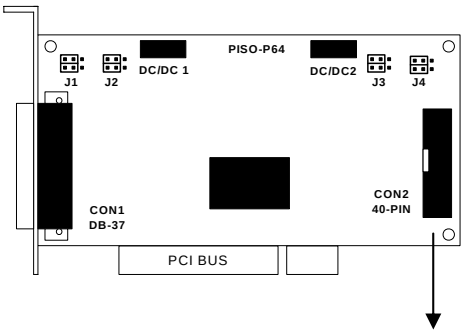
2.5 Pin Assignment of PISO-P32C32/P32A32



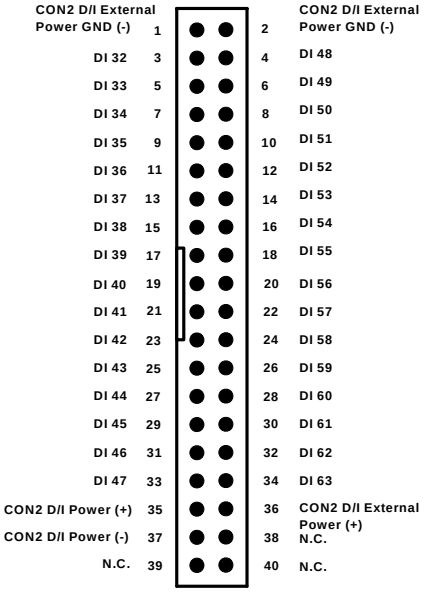
2.6 Pin Assignment of PISO-P64

CON1 Pin assignment

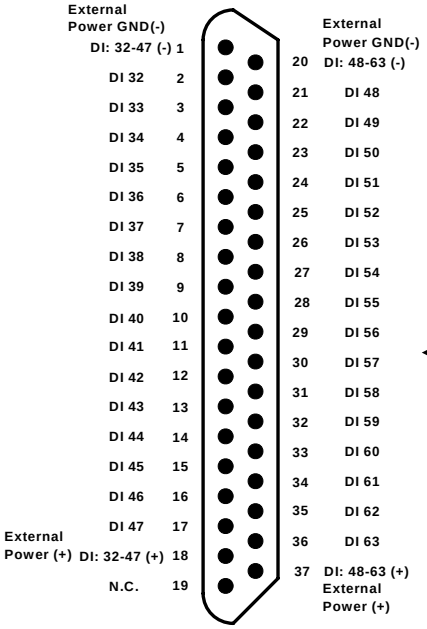


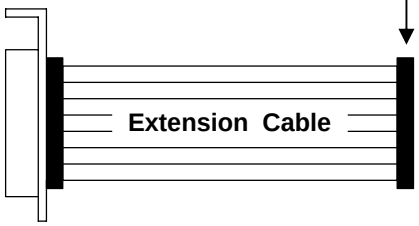


CON2 Pin assignment



CON2 Pin assignment



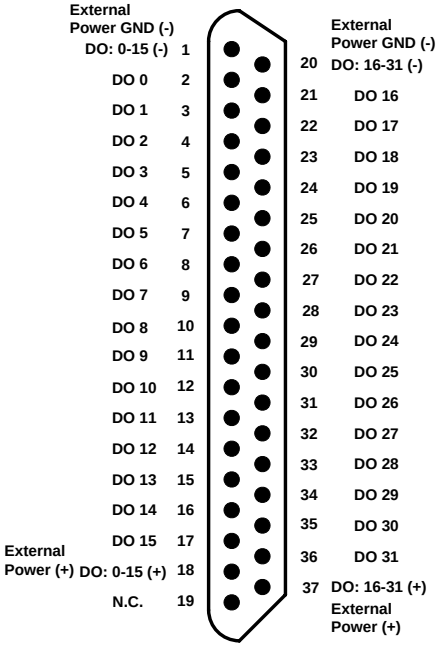


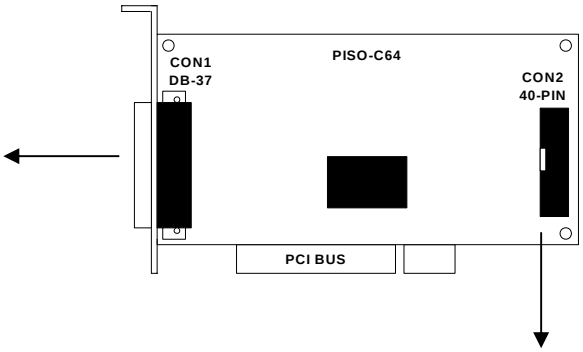
37-Pin cable conversion 40-Pin

Pin assignment of CON2 via extension

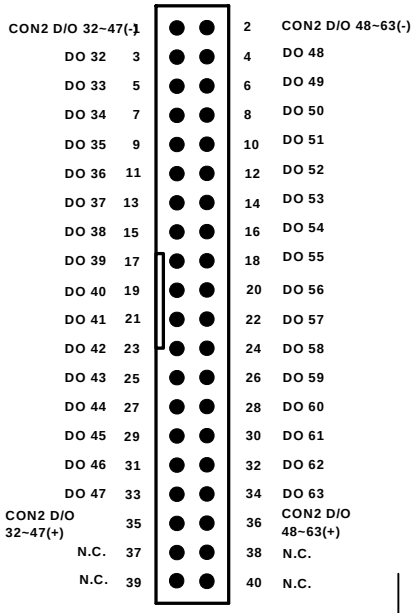
2.7 Pin Assignment of PISO-C64/A64

CON1 Pin assignment

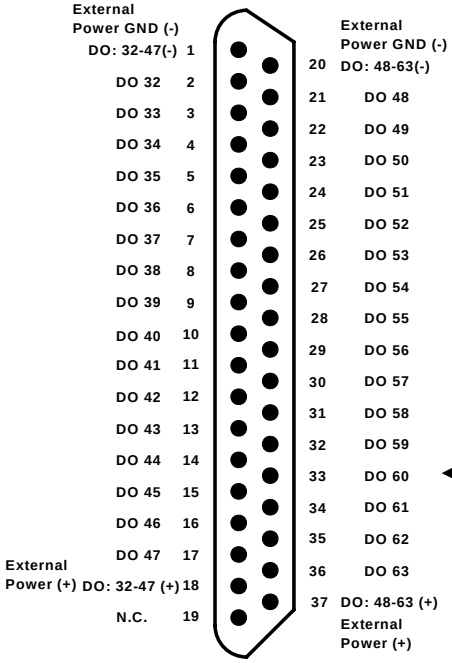


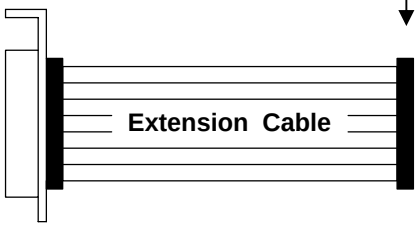


CON2 Pin assignment



CON2 Pin assignment





37-Pin cable conversion 40-Pin

Pin assignment of CON2 via extension

3. I/O Control Register

3.1 How to Find the I/O Address

The plug & play BIOS will assign a proper I/O address to every PIO/PISO series card in the power-on stage. The fixed IDs of PIO/PISO series card are given as follows:

OLD Version

Item	Sub-Vender	Sub-Device	Sub-Aux	Version
PISO-C64	0x80	0x08	0x00	Rev1.0~3.0
PISO-P64	0x80	0x08	0x10	Rev1.0~3.0
PISO-P32C32	0x80	0x08	0x20	Rev1.0~4.0
PISO-A64	0x80	0x08	0x50	Rev1.0~2.0
PISO-P32A32	0x80	0x08	0x70	Rev1.0~2.0

Vendor ID= 0xE159

Device ID= 0x02

New Version

Item	Sub-Vender	Sub-Device	Sub-Aux	Version
PISO-C64	0x0280	0x00	0x00	Rev4.0
PISO-P64	0x0280	0x00	0x10	Rev4.0
PISO-P32C32	0x0280	0x00	0x20	Rev5.0
PISO-A64	0x8280	0x00	0x50	Rev3.0
PISO-P32A32	0xC280	0x00	0x00	Rev3.3

Vendor ID= 0xE159

Device ID= 0x01

We provide all necessary functions as follows:

1. **PIO_DriverInit(&wBoard, wSubVendor, wSubDevice, wSubAux)**
2. **PIO_GetConfigAddressSpace(wBoardNo,*wBase,*wIrq, *wSubVendor,*wSubDevice, *wSubAux, *wSlotBus, *wSlotDevice)**
3. **Show_PIO_PISO(wSubVendor, wSubDevice, wSubAux)**

All functions are defined in PIO.H. Refer to Chapter 4 for more information. The important driver information is given as follows:

1. Resource-allocated information:

- wBase : BASE address mapping in this PC
- wIrq: IRQ channel number allocated in this PC

2. PIO/PISO identification information:

- wSubVendor: subVendor ID of this board
- wSubDevice: subDevice ID of this board
- wSubAux: subAux ID of this board

3. PC's physical slot information:

- wSlotBus: hardware slot ID1 in this PC's slot position
- wSlotDevice: hardware slot ID2 in this PC's slot position

The utility program, **PIO_PISO.EXE**, will detect & show all PIO/PISO cards installed in this PC. Refer to Chapter 5 for more information.

3.1.1 PIO_DriverInit

PIO_DriverInit(&wBoards, wSubVendor,wSubDevice,wSubAux)

- wBoards=0 to N → Number of boards found in this PC
- wSubVendor → SubVendor ID of board you are seeking
- wSubDevice → SubDevice ID of board you are seeking
- wSubAux → SubAux ID of board to you are seeking

This function can detect all PIO/PISO series cards with your system. Implementations is based on the PCI plug & play mechanism-1. It will find all PIO/PISO series cards installed in this system & save all their resource in the library.

Find all PIO/PISO cards in this PC

```
/* Step 1:Detect all PIO/PISO series cards in this PC */

wRetVal=PIO_DriverInit(&wBoards, 0xff, 0xff, 0xff);          /*Find all PIO_PISO*/
printf("\nThere are %d PIO_PISO Cards in this PC",wBoards);
if (wBoards==0 ) exit(0);

 /* Step2: Save resources for all PIO/ISO cards installed in this PC */
printf("\n-----------------------------------------------------");
for(i=0; i<wBoards; i++)
 {
PIO_GetConfigAddressSpace(i, &wBase, &wIrq, &wSubVendor, &wSubDevice, &wSubAux,
                                  &wSlotBus, &wSlotDevice);

 printf("\nCard_%d:wBase=%x,wIrq=%x,subID=[%x,%x,%x],
          SlotID=[%x,%x]",i,wBase,wIrq,wSubVendor,wSubDevice,
          wSubAux,wSlotBus,wSlotDevice);
 printf(" --> ");
 ShowPioPiso(wSubVendor,wSubDevice,wSubAux);
 }
```

Find all PISO-P32C32/P32A32 cards in this PC

```
/* Step1: Detect all PISO-P32C32/P32A32 cards first */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x20; /* for PISO_P32C32 */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x70; /* for PISO_P32A32 */
wRetVal=PIO_DriverInit(&wBoards, wSubVendor, wSubDevice, wSubAux);
printf("There are %d PISO-P32C32 Cards in this PC\n",wBoards);

/* Step2: Save resource of all PISO-P32C32/P32A32 cards installed in this PC */
for (i=0; i<wBoards; i++)
  {
PIO_GetConfigAddressSpace(i, &wBase, &wIrq, &wID1, &wID2, &wID3, &wID4, &wID5);
printf("\nCard_%d: wBase=%x, wIrq=%x", i, wBase, wIrq);
wConfigSpace[i][0]=wBaseAddress;                    /* save all resource of this card */
wConfigSpace[i][1]=wIrq;                            /* save all resource of this card */
 }
```

Find all PISO-P64 cards in this PC

```
/* Step1: Detect all PISO-P64 cards first */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x10;     /* for PISO_P64 */
wRetVal=PIO_DriverInit(&wBoards, wSubVendor,wSubDevice,wSubAux);
printf("There are %d PISO-P64 Cards in this PC\n",wBoards);

/* Step2: save resource of all PISO-P64 cards installed in this PC */
for (i=0; i<wBoards; i++)
  {
PIO_GetConfigAddressSpace(i,, &wBase, &wIrq, &wID1, &wID2, &wID3, &wID4, &wID5);
  printf("\nCard_%d: wBase=%x, wIrq=%x", i, wBase, wIrq);
 wConfigSpace[i][0]=wBaseAddress;                   /* save all resource of this card */
 wConfigSpace[i][1]=wIrq;                           /* save all resource of this card */
  }
```

Find all PISO-C64/A64 cards in this PC

```
/* Step1: Detect all PISO-C64 cards first */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x00;      /* for PISO-C64 */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x50;      /* for PISO-A64 */
wRetVal=PIO_DriverInit(&wBoards, wSubVendor,wSubDevice,wSubAux);
printf("Threr are %d PISO-C64 Cards in this PC\n",wBoards);
/* Step2: save resource of all PISO-C64/A64 cards installed in this PC */
for (i=0; i<wBoards; i++)
  {
PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&wID1,&wID2,&wID3,&wID4, &wID5);
  printf("\nCard_%d: wBase=%x, wIrq=%x", i, wBase, wIrq);
 wConfigSpace[i][0]=wBaseAddress;                    /* save all resource of this card */
 wConfigSpace[i][1]=wIrq;                            /* save all resource of this card */
}
```

3.1.2 PIO_GetConfigAddressSpace

PIO_GetConfigAddressSpace(wBoardNo,*wBase,*wIrq, *wSubVendor, *wSubDevice, *wSubAux, *wSlotBus,*wSlotDevice)

- wBoardNo=0 to N → totally N+1 boards found by PIO_DriveInit(...)
- wBase → base address of the board control word
- wIrq → allocated IRQ channel number of this board
- wSubVendor → subVendor ID of this board
- wSubDevice → subDevice ID of this board
- wSubAux → subAux ID of this board
- wSlotBus → hardware slot ID1 of this board
- wSlotDevice → hardware slot ID2 of this board

The user can use this function to save resources of all PIO/PISO cards installed in this system. Then the application program can directly control all functions of the PIO/PISO series card.

Find the configure address space for your PISO-P32C32/P32A32 card

```
/* Step1: Detect all PISO-P32C32 cards first */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x20;      /* for PISO_P32C32 */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x70;      /* for PISO_P32A32 */
wRetVal=PIO_DriverInit(&wBoards, wSubVendor,wSubDevice,wSubAux);
printf("There are %d PISO-P32C32 Cards in this PC\n",wBoards);

/* Step2: Save resources for all PISO-P32C32/P32A32 cards installed in this PC */
for (i=0; i<wBoards; i++)
  {
  PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&t1,&t2,&t3,&t4,&t5);
  printf("\nCard_%d: wBase=%x, wIrq=%x", i,wBase,wIrq);
 wConfigSpace[i][0]=wBaseAddress;                    /* save all resource of this card */
 wConfigSpace[i][1]=wIrq;                            /* save all resource of this card */
 }
/* Step3: Control the PISO-P32C32/P32A32 directly */
wBase=wConfigSpace[0][0];                    /* get base address the card_0 */
outport(wBase,1);                            /* enable all D/I/O operation of card_0 */
wBase=wConfigSpace[1][0];                    /* get base address the card_1 */
outport(wBase,1);                            /* enable all D/I/O operation of card_1 */
```

Find the configure address space of your PISO-P64 card

```
/* Step1: Detect all PISO-P64 cards first */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x10;      /* for PISO_P64 */
wRetVal=PIO_DriverInit(&wBoards, wSubVendor,wSubDevice,wSubAux);
printf("There are %d PISO-P64 Cards in this PC\n",wBoards);

/* Step2: Save resource of all PISO-P64 cards installed in this PC */
for (i=0; i<wBoards; i++)
  {
  PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&t1,&t2,&t3,&t4,&t5);
  printf("\nCard_%d: wBase=%x, wIrq=%x", i,wBase,wIrq);
 wConfigSpace[i][0]=wBaseAddress;                    /* save all resource of this card */
 wConfigSpace[i][1]=wIrq;                            /* save all resource of this card */
 }
/* Step3: Control the PISO-P64 directly */
wBase=wConfigSpace[0][0];                  /* get base address the card_0 */
outport(wBase,1);                          /* enable all D/I/O operation of card_0 */
wBase=wConfigSpace[1][0];                  /* get base address the card_1 */
outport(wBase,1);                          /* enable all D/I/O operation of card_1 */
```

Find the configure address space of your PISO-C64/A64 card

```
/* Step1: Detect all PISO-C64 cards first */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x00;      /* for PISO_C64 */
wSubVendor=0x80; wSubDevice=0x08; wSubAux=0x50;      /* for PISO_A64 */
wRetVal=PIO_DriverInit(&wBoards, wSubVendor,wSubDevice,wSubAux);
printf("There are %d PISO-C64 Cards in this PC\n",wBoards);

/* Step2: Save resource of all PISO-C64/A64 cards installed in this PC */
for (i=0; i<wBoards; i++)
  {  PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&t1,&t2,&t3,&t4,&t5);
   printf("\nCard_%d: wBase=%x, wIrq=%x", i,wBase,wIrq);
  wConfigSpace[i][0]=wBaseAddress;                    /* save all resource of this card */
  wConfigSpace[i][1]=wIrq;                            /* save all resource of this card */
  }
/* Step3: Control the PISO-C64/A64 directly */
wBase=wConfigSpace[0][0];                    /* get base address the card_0 */
outport(wBase,1);                            /* enable all D/I/O operation of card_0 */
wBase=wConfigSpace[1][0];                    /* get base address the card_1 */
outport(wBase,1);                            /* enable all D/I/O operation of card_1 */
```

3.1.3 Show_PIO_PISO

Show_PIO_PISO(wSubVendor, wSubDevice, wSubAux)

- wSubVendor → subVendor ID of board you are seeking
- wSubDevice → subDevice ID of board you are seeking
- wSubAux → subAux ID of board you are seeking

This function will show a text string for these special subIDs. This text string is the same as defined in PIO.H

The demo program is as follows:

```
wRetVal=PIO_DriverInit(&wBoards,0xff,0xff,0xff);  /* find all PIO_PISO series card*/
printf("\nThere are %d PIO_PISO Cards in this PC",wBoards);
if (wBoards==0 ) exit(0);

printf("\n-----------------------------------------------------");
for(i=0; i<wBoards; i++)
{
PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&wSubVendor,
        &wSubDevice,&wSubAux,&wSlotBus,&wSlotDevice);

printf("\nCard_%d:wBase=%x,wIrq=%x,subID=[%x,%x,%x],
        SlotID=[%x,%x]",i,wBase,wIrq,wSubVendor,wSubDevice,
        wSubAux,wSlotBus,wSlotDevice);
printf(" --> ");
ShowPioPiso(wSubVendor,wSubDevice,wSubAux);
}
```

3.2 The Assignment of I/O Address

The Plug & Play BIOS will assign the proper I/O address to each PIO/PISO series card. If there is only one PIO/PISO board, identify the board as card_0. However, if there are two PIO/PISO boards in the system, identifying which board is card_0 becomes more difficult? The software driver can support a max of 16 boards.

It is difficult to find the card NO. The easiest way to identify which card is card_0 is to use wSlotBus & wSlotDevice as following:

1. Remove all PISO-P32C32/P32A32/P64/C64/A64 cards from this PC
2. Install one PISO-P32C32/P32A32/P64/C64/A64 card into the PC's PCI_slot1. Run PIO_PISO.EXE & record the result wSlotBus1 & wSlotDevice1
3. Remove all PISO-P32C32/P32A32/P64/C64/A64 from this PC
4. Install one PISO-P32C32/P32A32/P64/C64/A64 into the PC's PCI_slot2. Run PIO_PISO.EXE & record the wSlotBus2 & wSlotDevice2
5. Repeat (3) & (4) for all PCI_slots. Record all results wSlotBus? & wSlotDevice?.

Here is a possible sample record:

PC's PCI slot	WslotBus	WSlotDevice
Slot_1	**0**	**0x07**
Slot_2	**0**	**0x08**
Slot_3	**0**	**0x09**
Slot_4	**0**	**0x0A**
PCI-BRIDGE		
Slot_5	**1**	**0x0A**
Slot_6	**1**	**0x08**
Slot_7	**1**	**0x09**
Slot_8	**1**	**0x07**

The above procedure will record all wSlotBus? & wSlotDevice? in this PC, with the values mapped to the card's physical slot in the PC. This mapping will not be changed for any PIO/PISO cards. Because this mapping won't change, it can be used to identify the specified PIO/PISO card as follows:

Step1: Record all wSlotBus? & wSlotDevice?

Step2: Use PIO_GetConfigAddressSpace(…) to get the wSlotBus & wSlotDevice for the specified card.

Step3: The user can identify the specified PIO/PISO card if he compares the two results.

3.3 Enabling I/O Operation

When the PC is first powered-on, D/I/O operations are disabled. The enable/disable of D/I/O is controlled by the RESET\ signal. The powered-on states are given as follows:

- All D/I/O operations are disabled
- All D/O latch register are clear

The user has to initialize before using these D/I/O parts. To do so, follow these recommended steps:

Step 1: Enable all D/I/O operation.

Step 2: Read from D/I or write to D/O

Refer to DEMO1.C for demo program.

3.4 The I/O Address Map

PIO/PISO series card I/O addresses are automatically assigned by the main ROM BIOS of the main board. You can also re-assign the I/O addresses. **It is strongly recommended to use the assigned I/O address. The Plug & Play BIOS will assign the proper I/O address to each PIO/PISO series card.**

3.4.1 PISO-P32C32/P32A32 I/O Mapping

The PISO-P32C32/P32A32 I/O addresses are mapped as follows:

Address	Read	Write
Wbase+0	RESET\ control register	Same
Wbase+2	Aux control register	Same
Wbase+3	Aux data register	Same
Wbase+5	INT mask control register	Same
Wbase+7	Aux pin status register	Same
Wbase+0x2a	INT polarity control register	Same
Wbase+0xc0	Read data from DI_0 ~ DI_7	Write data to DO_0 to DO_7
Wbase+0xc4	Read data from DI_8 ~ DI_15	Write data to DO_8 to DO_15
Wbase+0xc8	Read data from DI_16 ~ DI_23	Write data to DO_16 to DO_23
Wbase+0xcc	Read data from DI_24 ~ DI_31	Write data to DO_24 to DO_31

Note. Refer to Sec. 3.1 for more information about wBase.

```
outportb(wBase+0xc0,Val);          /* write to D/O 0~7     */
outportb(wBase+0xc4,Val);          /* write to D/O 8~15    */
outportb(wBase+0xc8,Val);          /* write to D/O 16~23   */
outportb(wBase+0xcc,Val);          /* write to D/O 24~31   */

Val=inportb(wBase+0xc0);           /* read from D/I 0~7    */
Val=inportb(wBase+0xc4);           /* read from D/I 8~15   */
Val=inportb(wBase+0xc8);           /* read from D/I 16~23  */
Val=inportb(wBase+0xcc);           /* read from D/I 24~31  */
```

3.4.2 PISO-P64 I/O Mapping

The PISO-P64 I/O addresses are mapped as follows:

Address	**Read**	**Write**
wBase+0	RESET\ control register	Same
wBase+2	Aux control register	Same
wBase+3	Aux data register	Same
WBase+5	INT mask control register	Same
Wbase+7	Aux pin status register	Same
Wbase+0x2a	INT polarity control register	Same
Wbase+0xc0	Read data from DI_0 ~ DI_7	Reserved
Wbase+0xc4	Read data from DI_8 ~ DI_15	Reserved
Wbase+0xc8	Read data from DI_16 ~ DI_23	Reserved
Wbase+0xcc	Read data from DI_24 ~ DI_31	Reserved
WBase+0xd0	Read data from DI_32 ~ DI_39	Reserved
WBase+0xd4	Read data from DI_40 ~ DI_47	Reserved
WBase+0xd8	Read data from DI_48 ~ DI_55	Reserved
WBase+0xdc	Read data from DI_56 ~ DI_63	Reserved

Note. Refer to Sec. 3.1 for more information about wBase.

```
Val=inportb(wBase+0xc0);          /* read from D/I 0~7     */
Val=inportb(wBase+0xc4);          /* read from D/I 8~15    */
Val=inportb(wBase+0xc8);          /* read from D/I 16~23 */
Val=inportb(wBase+0xcc);          /* read from D/I 24~31 */

Val=inportb(wBase+0xd0);          /* read from D/I 32~39  */
Val=inportb(wBase+0xd4);          /* read from D/I 40~47  */
Val=inportb(wBase+0xd8);          /* read from D/I 48~55  */
Val=inportb(wBase+0xdc);          /* read from D/I 56~63  */
```

3.4.3 PISO-C64 I/O Mapping

The PISO-C64/A64 I/O addresses are mapped as follows:

Address	**Read**	**Write**
wBase+0	RESET\ control register	Same
wBase+2	Aux control register	Same
wBase+3	Aux data register	Same
wBase+5	INT mask control register	Same
wBase+7	Aux pin status register	Same
wBase+0x2a	INT polarity control register	Same
wBase+0xc0	Reserved	Write data to DO_0 to DO_7
wBase+0xc4	Reserved	Write data to DO_8 to DO_15
wBase+0xc8	Reserved	Write data to DO_16 to DO_23
wBase+0xcc	Reserved	Write data to DO_24 to DO_31
wBase+0xd0	Reserved	Write data to DO_32 to DO_39
wBase+0xd4	Reserved	Write data to DO_40 to DO_47
wBase+0xd8	Reserved	Write data to DO_48 to DO_55
wBase+0xdc	Reserved	Write data to DO_56 to DO_63

Note. Refer to Sec. 3.1 for more information about wBase.

```
outportb(wBase+0xc0,Val);          /* write to D/O 0~7     */
outportb(wBase+0xc4,Val);          /* write to D/O 8~15    */
outportb(wBase+0xc8,Val);          /* write to D/O 16~23 */
outportb(wBase+0xcc,Val);          /* write to D/O 24~31 */

outportb(wBase+0xd0,Val);          /* write to D/O 32~39 */
outportb(wBase+0xd4,Val);          /* write to D/O 40~47 */
outportb(wBase+0xd8,Val);          /* write to D/O 48~55 */
outportb(wBase+0xdc,Val);          /* write to D/O 56~63 */
```

3.4.4 RESET\ Control Register

(Read/Write): wBase+0

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	RESET\

Note. Refer to Sec. 3.1 for more information about wBase.

When the PC is first powered-on, the RESET\ signal is in Low-state. **This will disable all D/I/O operations.** The user has to set the RESET\ signal to High-state before any D/I/O commands are given.

```
outportb(wBase,1);        /*  RESET\ = High → all D/I/O are enabled now */
outportb(wBase,0);        /*  RESET\ = Low → all D/I/O are disabled now */
```

3.4.5 AUX Control Register

(Read/Write): wBase+2

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Aux7	Aux6	Aux5	Aux4	Aux3	Aux2	Aux1	Aux0

Note. Refer to Sec. 3.1 for more information about wBase.

Aux?=0→ this Aux is used as a D/I

Aux?=1→ this Aux is used as a D/O

When the PC is first powered-on, All Aux? signals are in Low-state. All Aux? are designed as D/I for all PIO/PISO series cards. Please set all Aux? to D/I state.

3.4.6 AUX Data Register

(Read/Write): wBase+3

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Aux7	Aux6	Aux5	Aux4	Aux3	Aux2	Aux1	Aux0

Note. Refer to Sec. 3.1 for more information about wBase.

When the Aux? is used as D/O, the output state is controlled by this register. This register is designed for future applications, Please do not change this register.

3.4.7 INT Mask Control Register

(Read/Write): wBase+5

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	0	0	0	0	0	0

Note. Refer to Sec. 3.1 for more information about wBase.

This register is designed for future applications, Please do not change this register.

3.4.8 AUX Status Register

(Read/Write): wBase+7

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Aux7	Aux6	Aux5	Aux4	Aux3	Aux2	Aux1	Aux0

Note. Refer to Sec. 3.1 for more information about wBase.

Aux0-3=reserved, aux4-7=Aux-ID.

4. The applications of Digital I/O

4.1 The PISO-P32C32/P32A32

- **The circuit diagram of D/O of PISO-P32C32/P32A32 is as follows:**

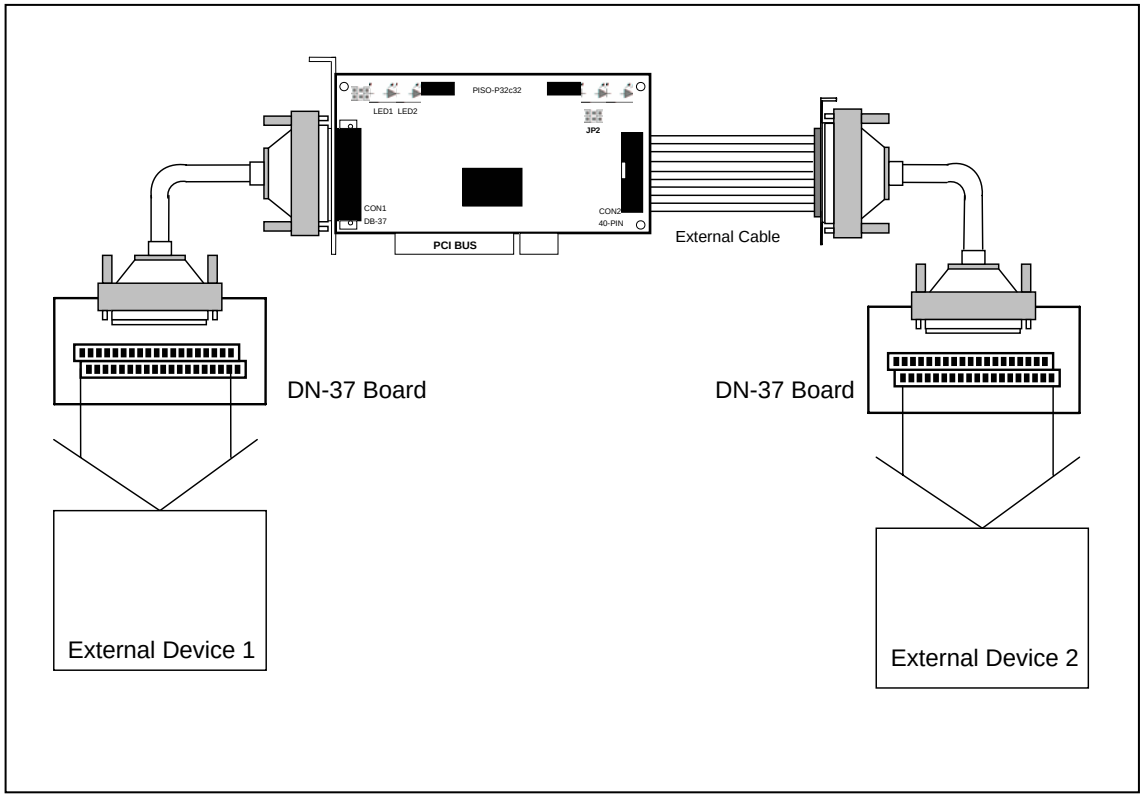
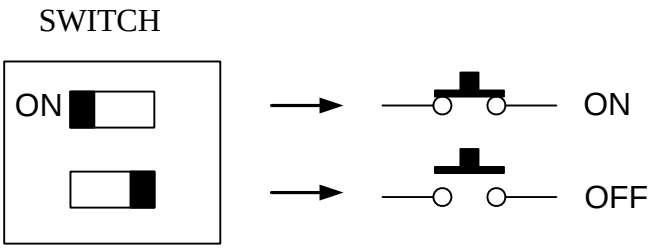


Figure 4-1-1. Digital inputs/outputs for PISO-P32C32/P32A32

- Figure 4-1-2(PISO-P32C32) shows the circuit diagram of external device 1
- Figure 4-1-3(PISO-P32A32) shows the circuit diagram of external device 1
- Figure 4-1-4(PISO-P32C32) shows the circuit diagram of external device 2
- Figure 4-1-5(PISO-P32A32) shows the circuit diagram of external device 2



- **Here's the circuit diagram for external device 1:**

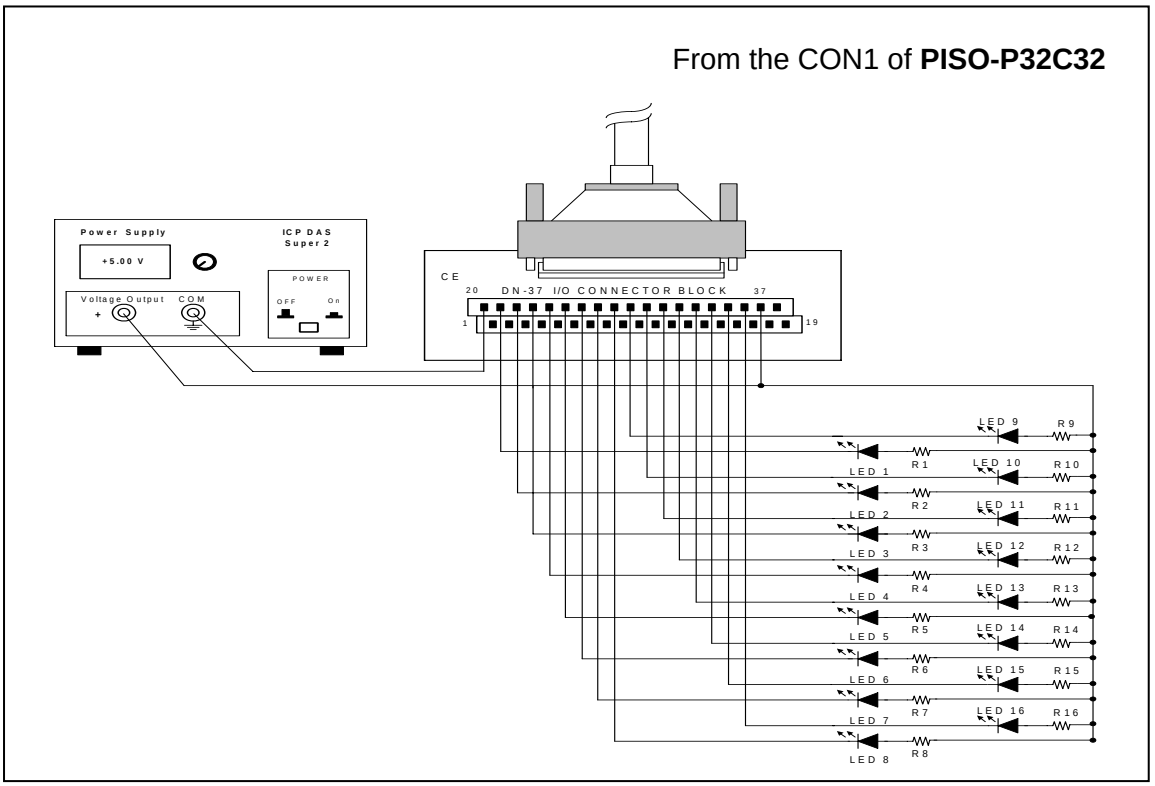


Figure 4-1-2. The circuit diagram of external device 1 for the digital outputs of **PISO-P32C32**

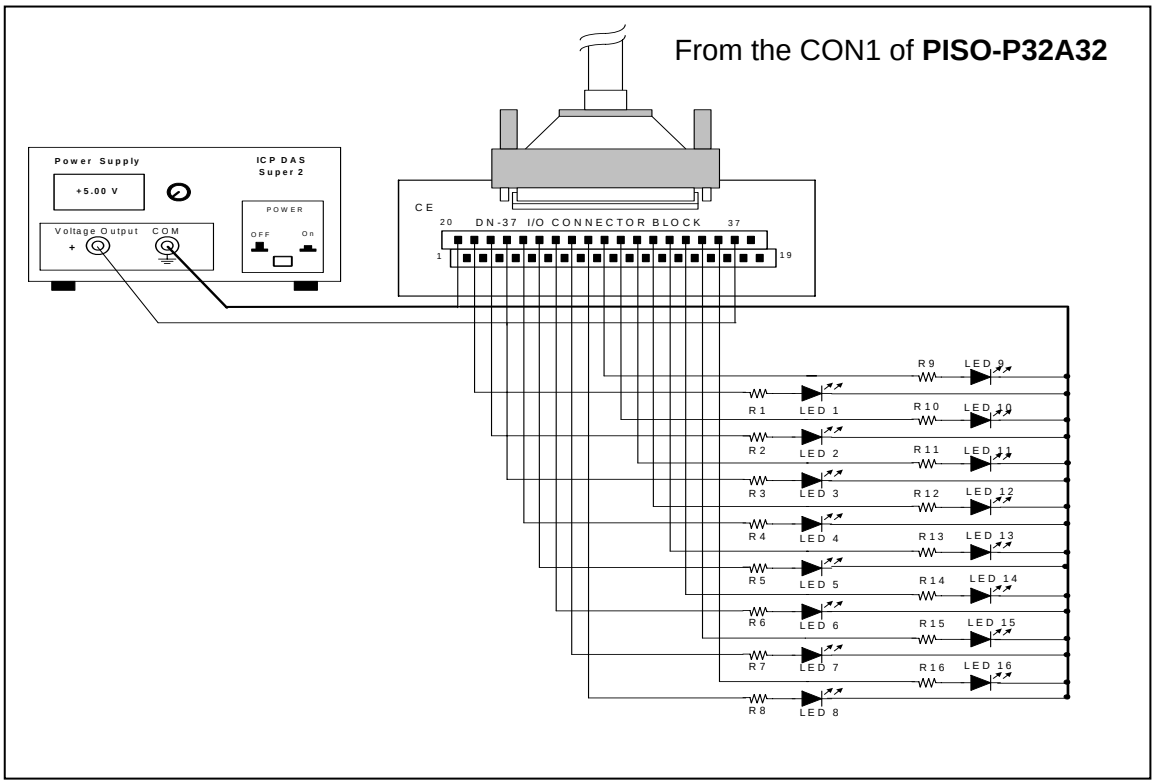


Figure 4-1-3. The circuit diagram of external device 1 for the digital outputs of **PISO-P32A32**

- Resistance for R1~R16 is 330 ohm.
- LEDs 1-6 are light-emitting diodes.
- Pin-1/20 are the GND signal for DI_0~DI_15 / DO_0~DO_15
- Pin-18/37 are the voltage (+) signal for DI_0~DI_15 / DO_0~DO_15 (input DC +5V~+24V)

- **Here's the circuit diagram for external device 2:**

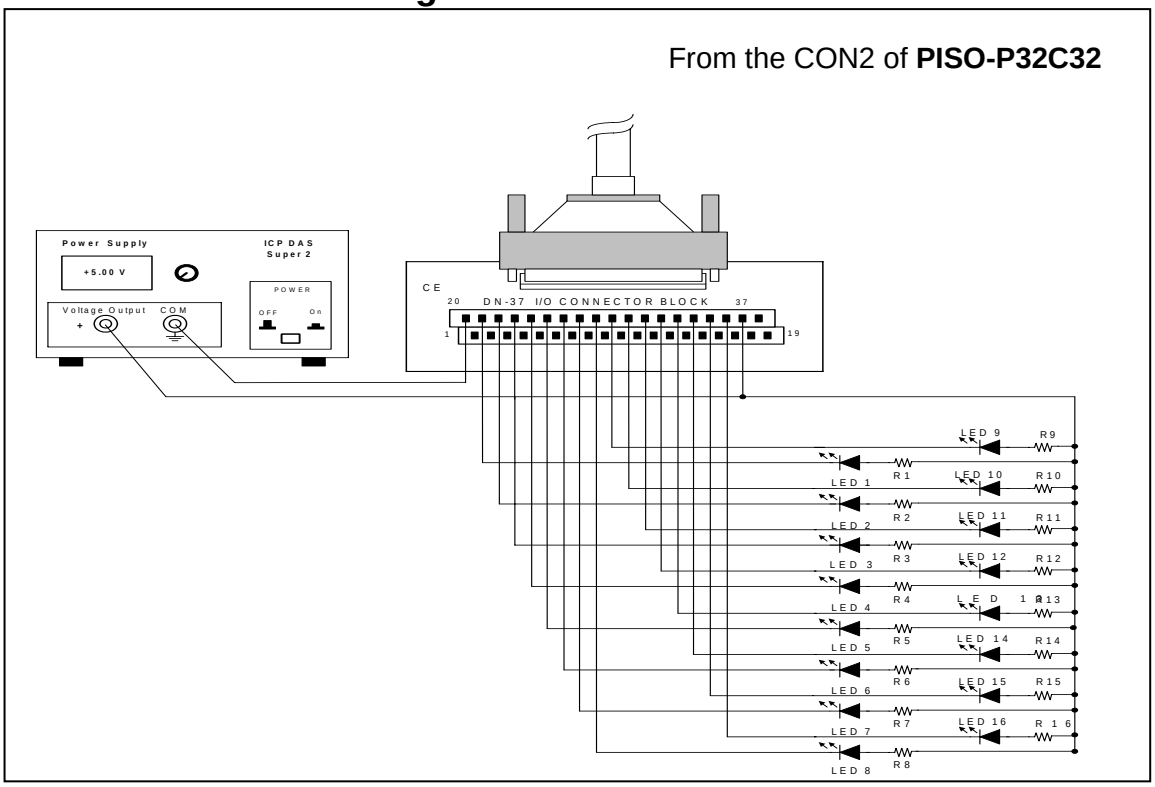


Figure 4-1-4. The circuit diagram of external device 2 for the digital outputs of **PISO-P32C32**

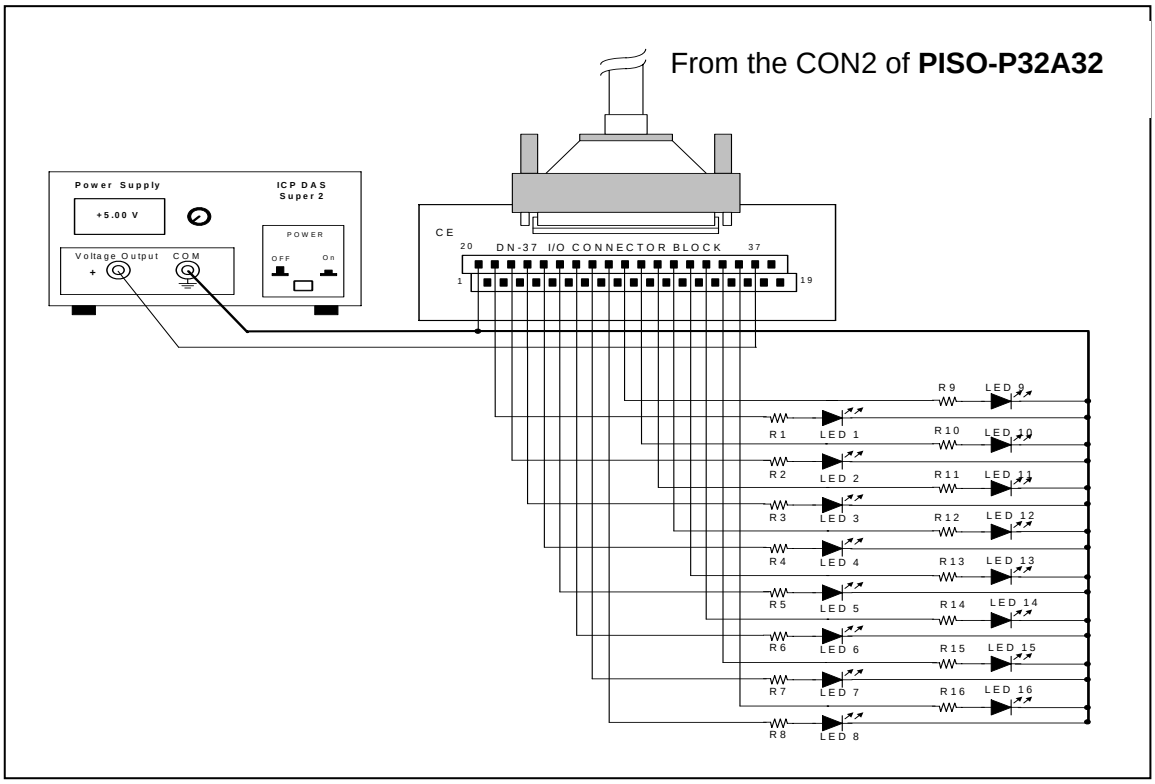


Figure 4-1-5. The circuit diagram of external device 2 for the digital outputs of **PISO-P32A32**

- Resistance for R17~R32 is 330 ohm.
- LEDs 17~32 are light emitting diodes.
- Pin-1/20 are the GND signal for DI_16~DI_31 / DO_16~DO_31.
- Pin-18/37 are the voltage (+) signal for DI_16~DI_31 / DO_16~DO_31 (input DC 5V~24V).

- **Here's the circuit diagram for D/I of PISO-P32C32/P32A32:**

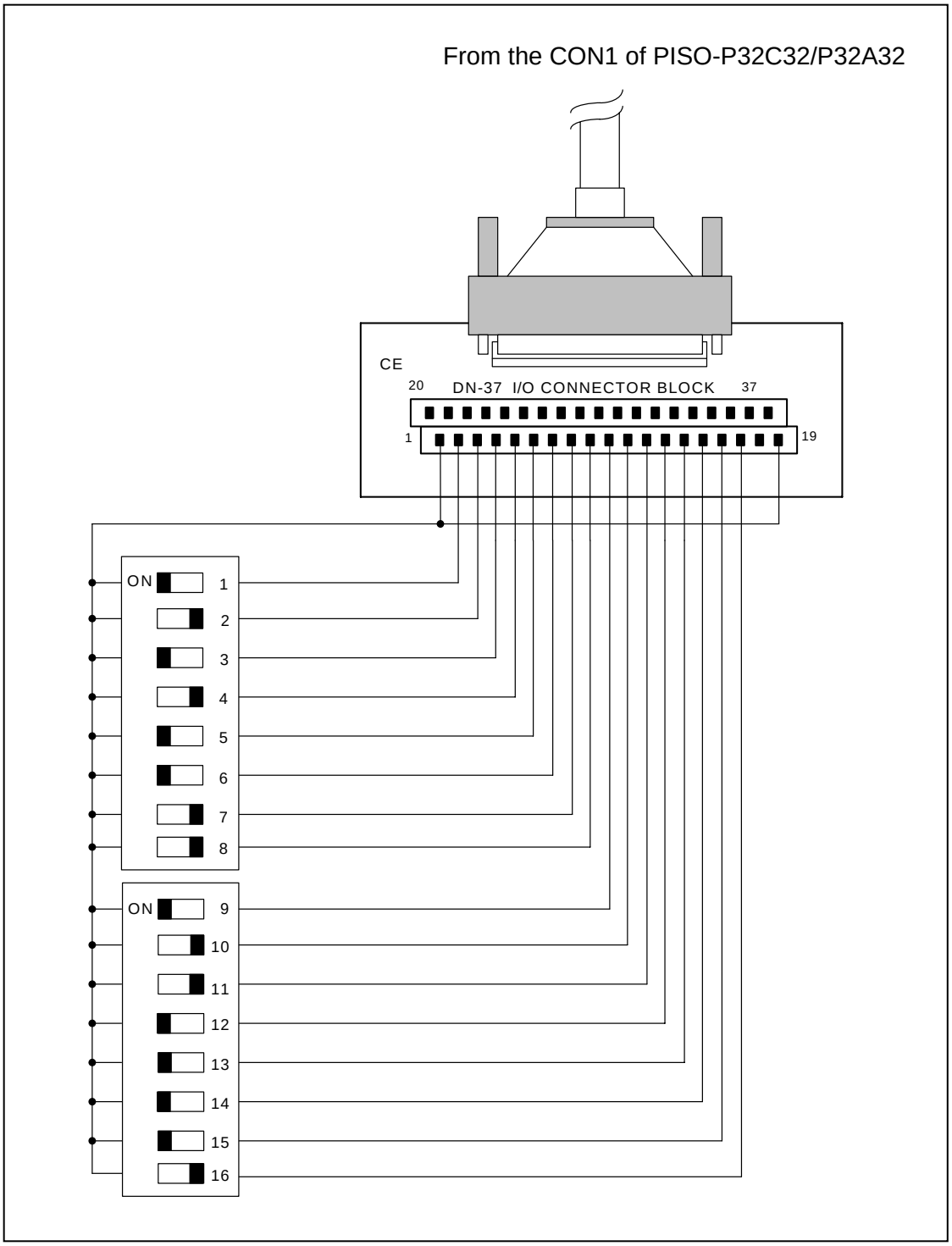


Figure 4-1-6. The circuit diagram of external device 1 for the D/I of **PISO-P32C32/P32A32**

- The D/I of CON1 for PISO-P32C32 is set to **internal power**.
- Pin-19 is the GND signal for DI_0~DI_15.
- Pin-18 is the voltage (+) signal for DI_0~DI_15(input DC +5V~+24V).

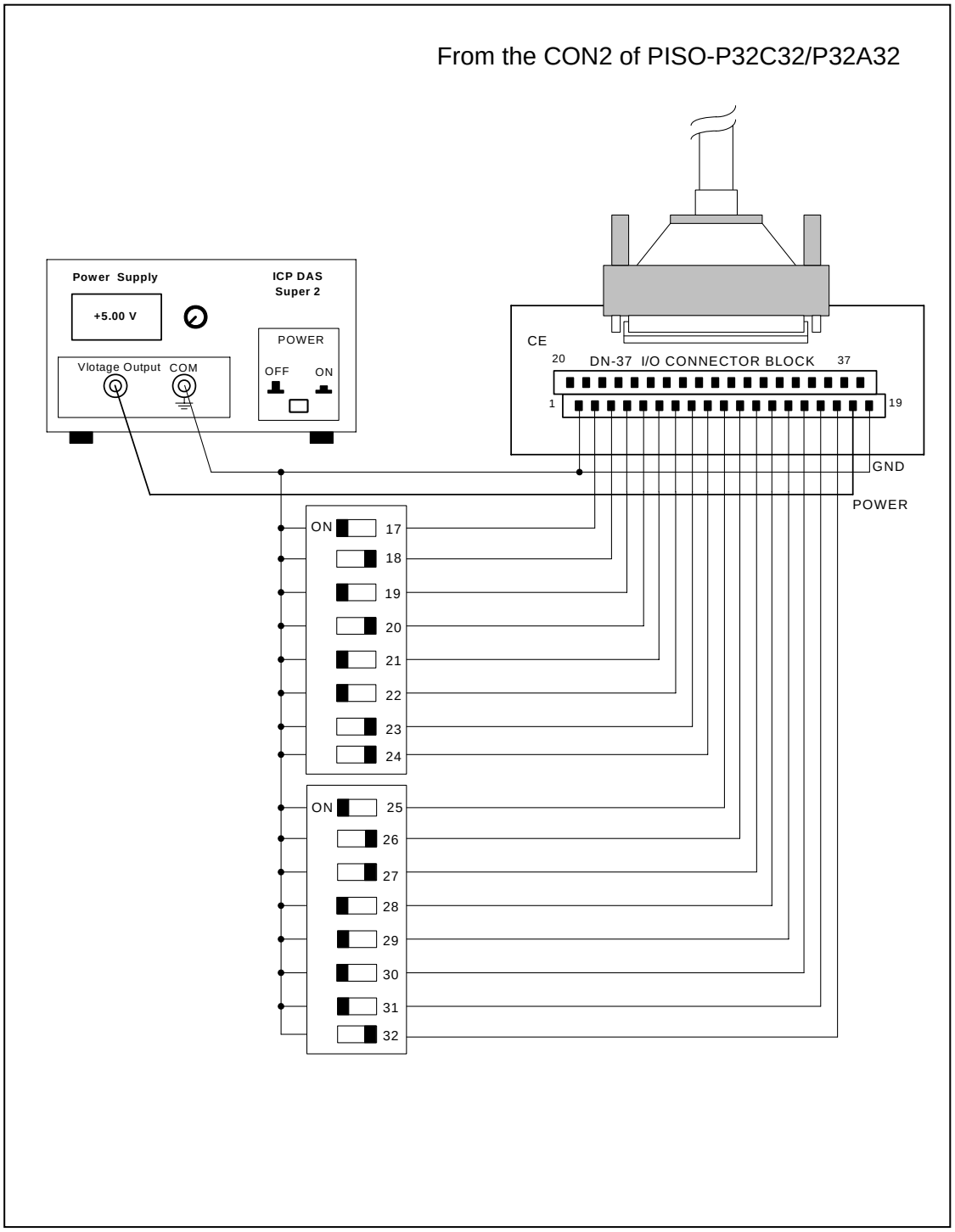


Figure 4-1-6. The circuit diagram of external device 2 for the D/I of **PISO-P32C32/P32A32**

- The D/I of CON1 of PISO-P32C32 is set to **external power.**
- Pin-19 is the GND signal for DI_0~DI_15.
- Pin-18 is the voltage (+) signal for DI_0~DI_15(input DC +5V~+24V)

4.2 The example of PISO-P64

- **Here's the circuit diagram of D/I for PISO-P64:**

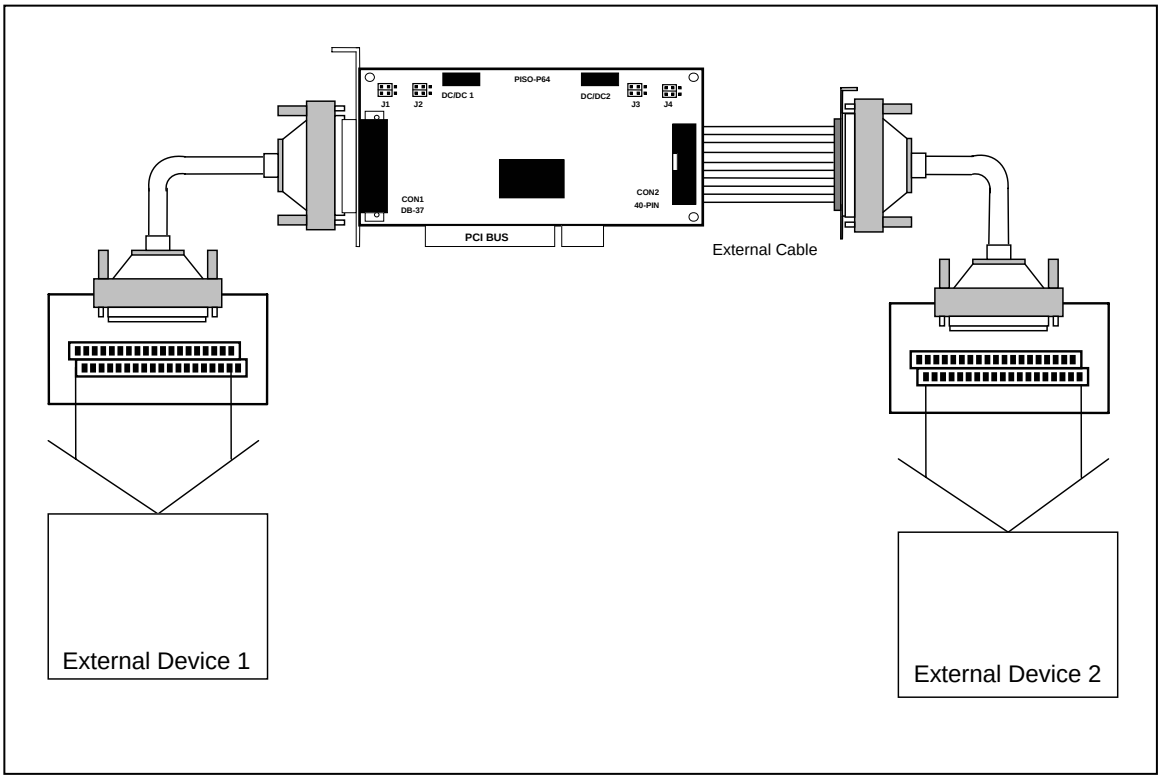
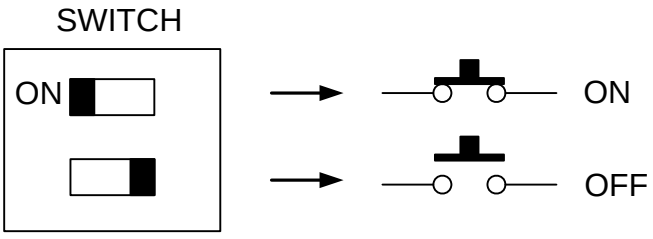


Figure 4-2-1. Digital inputs for PISO-P64

- Refer to Figure 4-2-2 for the circuit diagram of external device 1
- Refer to Figure 4-2-3 for the circuit diagram of external device 2



Here's the circuit diagram for external device 1:

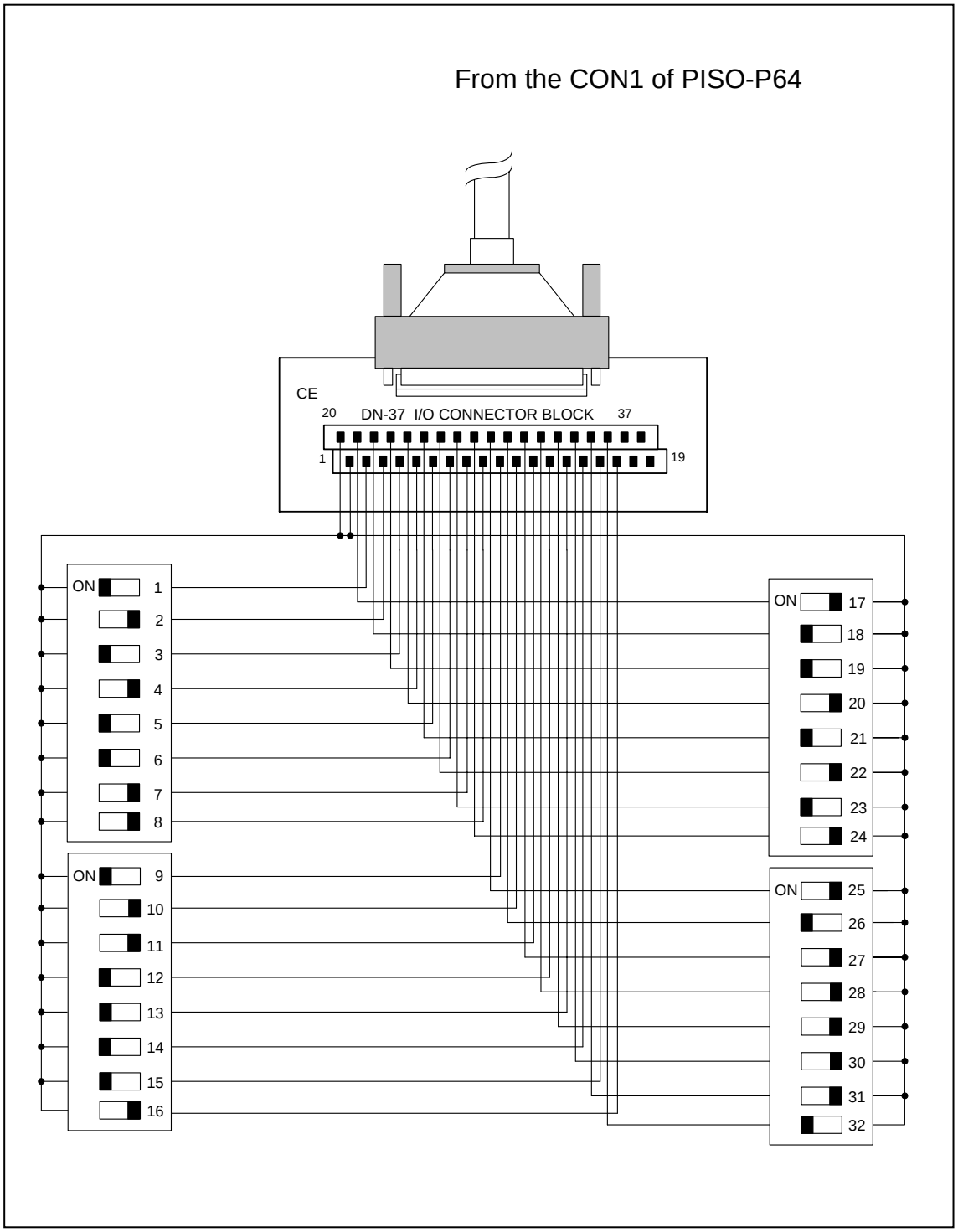


Figure 4-2-2. The circuit diagram of external device 2 for the digital inputs of **PISO-P64**

- The D/I of CON1 of PISO-P64 is set to **internal power**.

Here's the circuit diagram of external device 2:

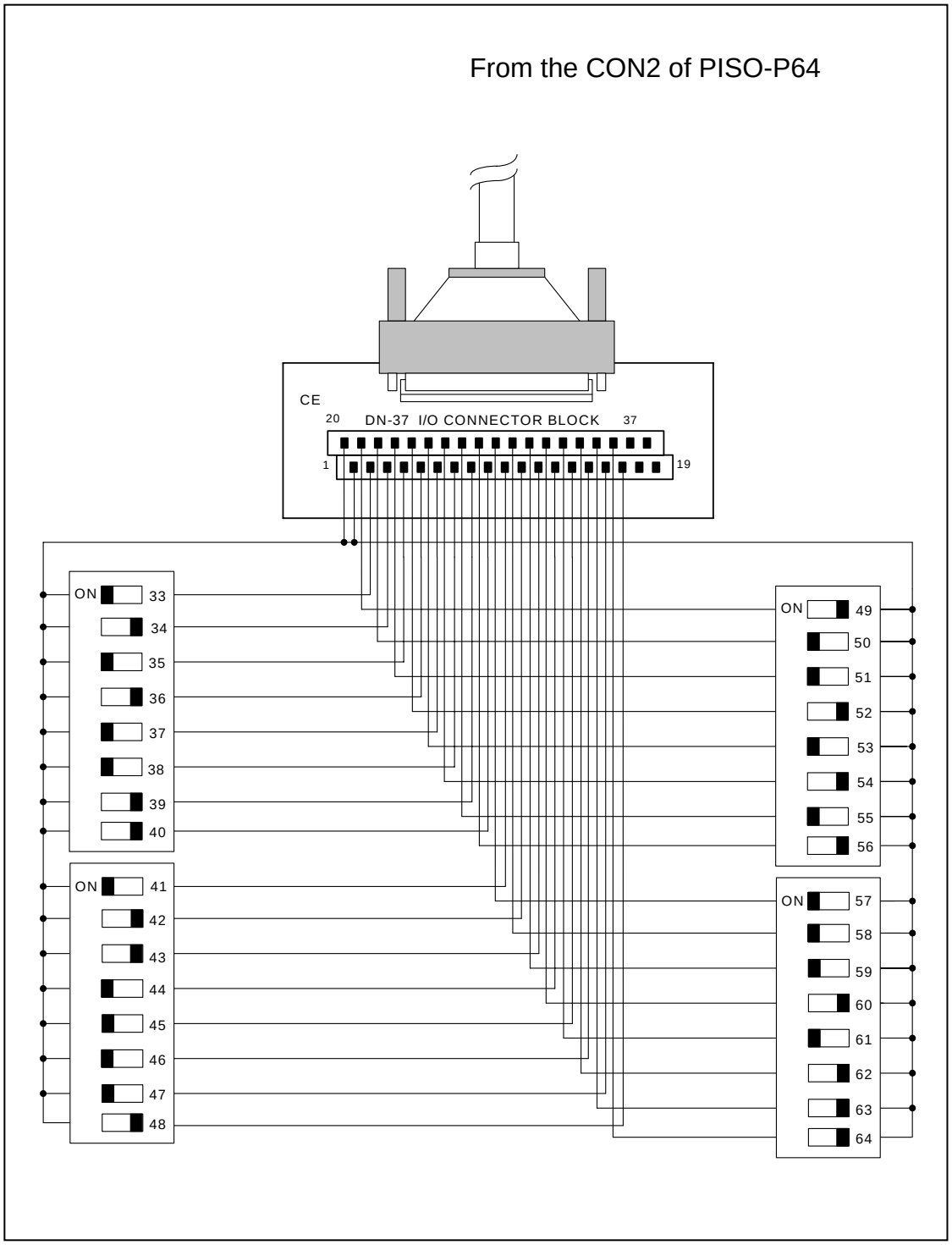


Figure 4-2-3. The circuit diagram of external device 2 for the digital inputs of **PISO-P64**

- The D/I of CON2 of PISO-P64 is set to internal power.

4.3 The example of PISO-C64/A64

- **Here's the D/O circuit diagram for PISO-C64/A64:**

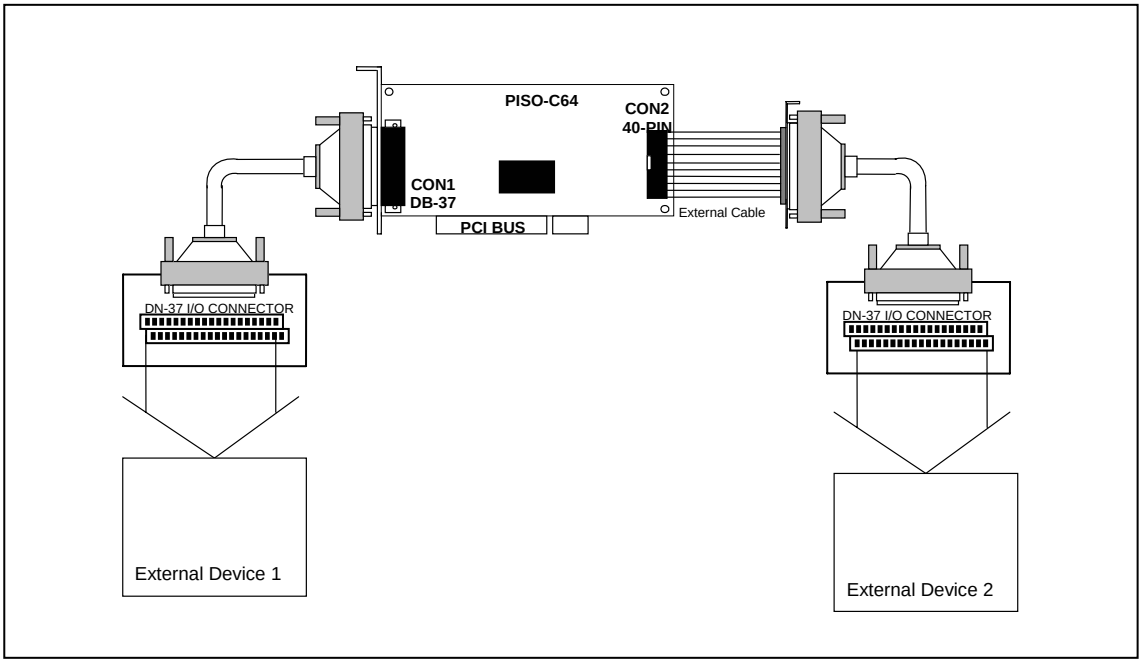


Figure 4-3-1. The example of digital outputs for PISO-C64/A64

- Refer to Figure 4-3-2 for the circuit diagram of external device 1:
- Refer to Figure 4-3-3 for the circuit diagram of external device 2:

Here's the circuit diagram for external device 1:

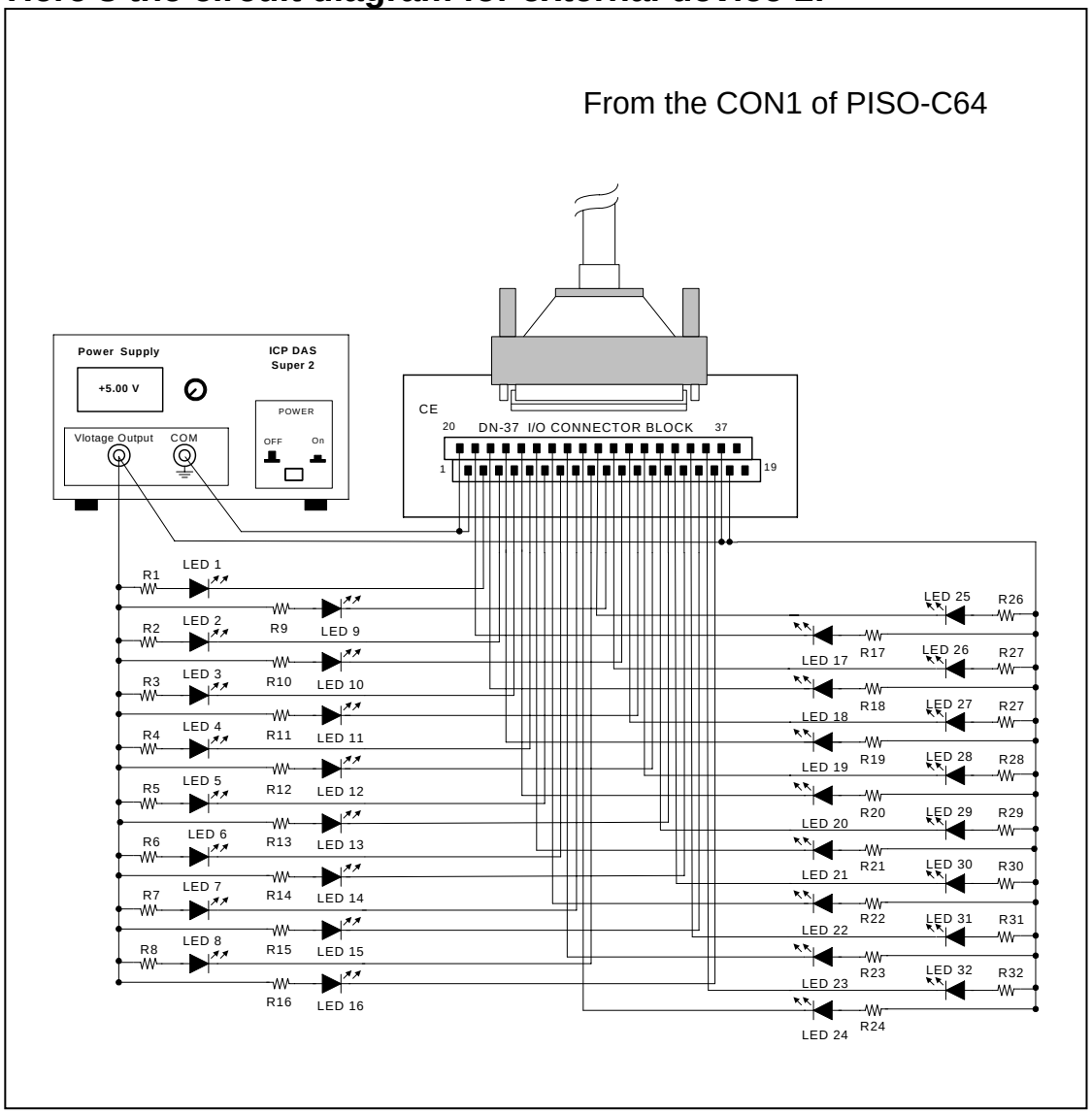


Figure 4-3-2. The circuit diagram of external device 1 for the digital outputs of **PISO-C64**

- The resistance of R1~R32 is 330 ohm.
- LEDs 1~32 are light-emitting diodes.
- Pin-1/20 are GND signal for DO_0~DO_15 / DO_16~DO_31.
- Pin-18/37 are voltage (+) signal for DO_0~DO_15 / DO_16~DO_31 (input DC +5V~+24V).

Here's the circuit diagram for external device 1:

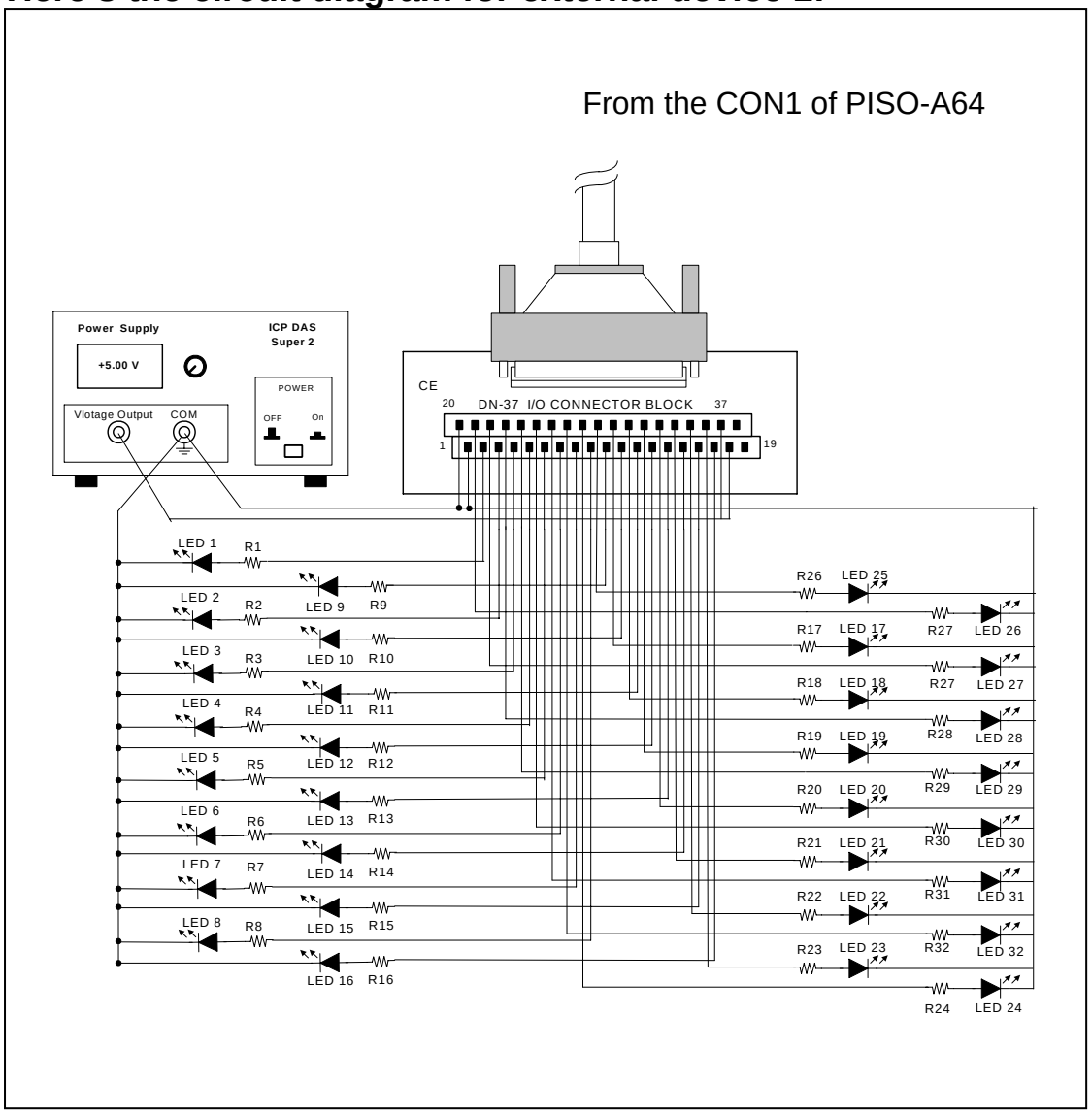


Figure 4-3-2. The circuit diagram of external device 1 for the digital outputs of **PISO-A64**

- The resistance of R1~R32 is 330 ohm.
- LEDs 1~32 are light-emitting diodes.
- Pin-1/20 are GND signal for DO_0~DO_15 / DO_16~DO_31.
- Pin-18/37 are voltage(+) signal for DO_0~DO_15 / DO_16~DO_31 (input DC +5V~+24V)

.

Here's the circuit diagram for external device 2:

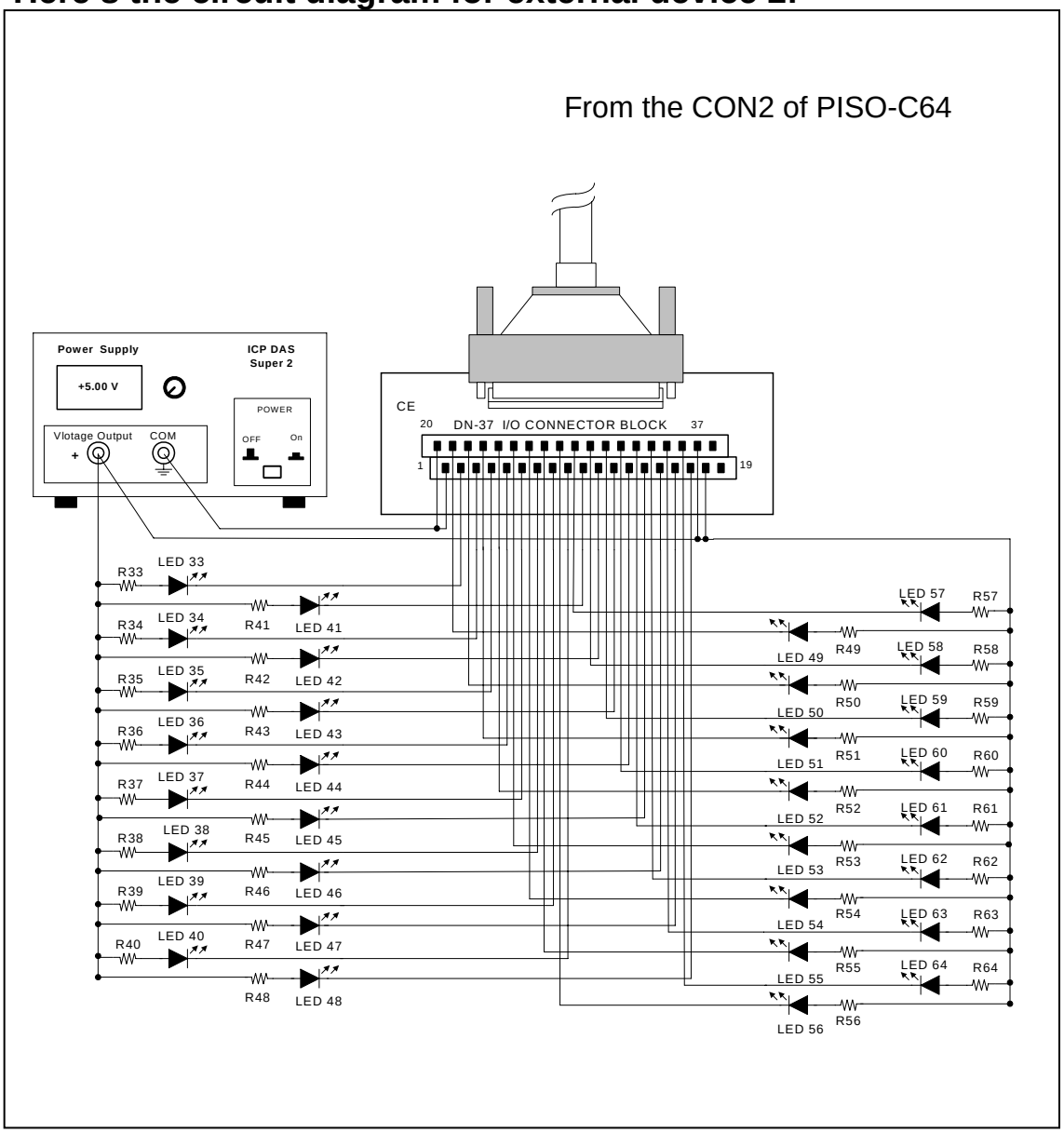


Figure 4-3-3. The circuit diagram of external device 2 for the digital outputs of PISO-C64

- The resistance of R33~R64 is 330 ohm.
- LEDs 33~64 are light-emitting diodes.
- Pin-1/20 are GND signal for DO_32~DO_47 / DO_48~DO_63.
- Pin-18/37 are voltage(+) signal for DO_32~DO_47 / DO_32~DO_63 (input DC +5V~+24V).

Here's the circuit diagram for external device 2:

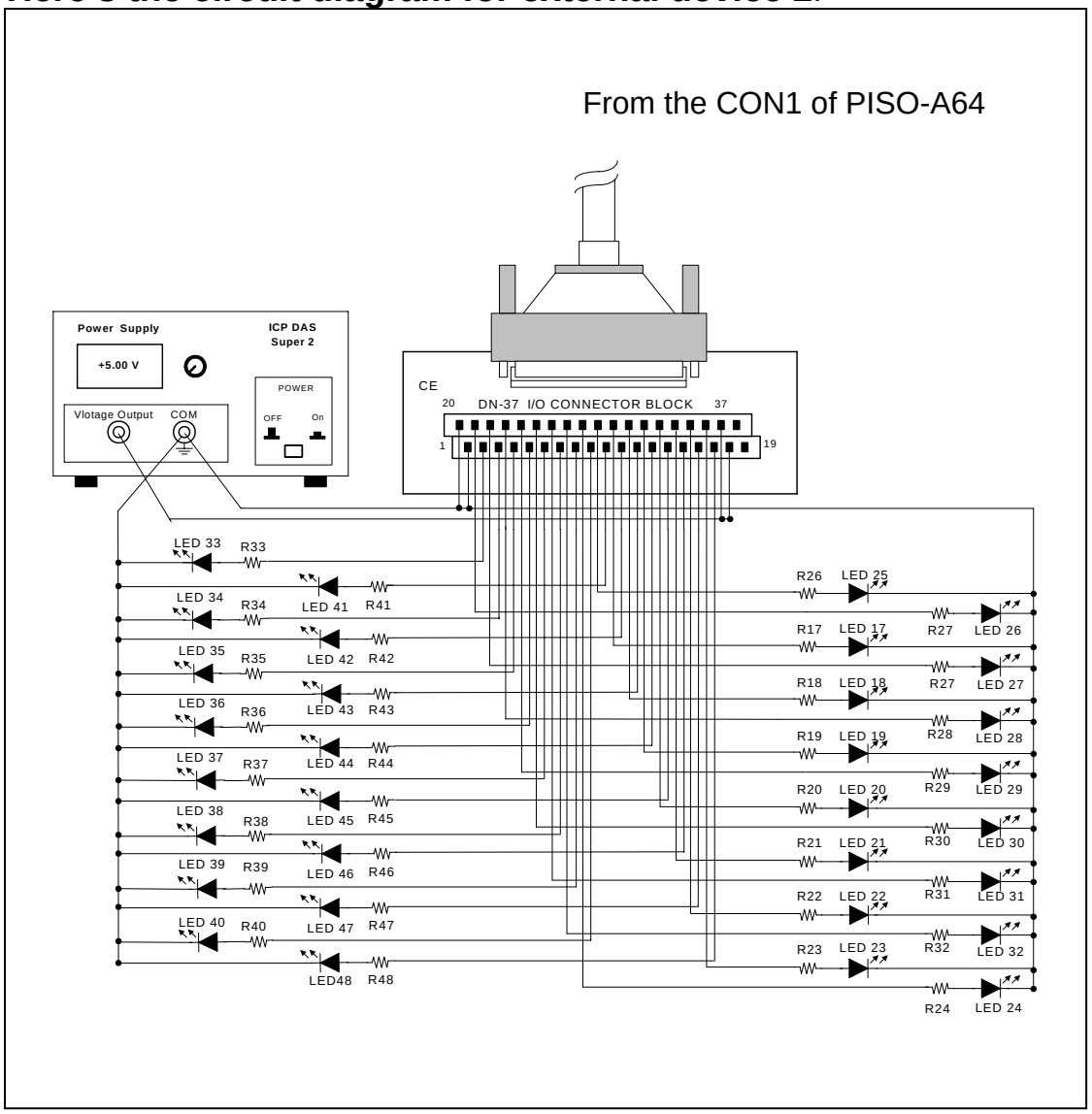


Figure 4-3-4. The circuit diagram of external device 1 for the digital outputs of PISO-A64

- The resistance of R1~R32 is 330 ohm.
- LEDs 1~32 are light-emitting diodes.
- Pin-1/20 are GND signal for DO_0~DO_15 / DO_16~DO_31.
- Pin-18/37 are voltage(+) signal for DO_0~DO_15 / DO_16~DO_31 (input DC +5V~+24

5. Demo Program

There are many demo programs provided on floppy disk or CD-ROM. After software installation, the following driver will be installed into your hard disk:

5.1 Program file list for PISO-P32C32/P32A32

- ...\P32C32P32A32\TC>*.* → for Turbo C 2.xx or above
- ...\P32C32P32A32\BC>*.* → for Borland C++ 3.X above
- ...\P32C32P32A32\MSC>*.* → for Microsoft C 5.X above

- ...\P32C32P32A32\TC\LIB>*.* → for library source code
- ...\P32C32P32A32\TC\DEMO>*.* → demo program source code
- ...\P32C32P32A32\TC\DIAG>*.* → pio_piso auto detect program

- ...\P32C32P32A32\TC\LIB\PIO.H → library header file
- ...\P32C32P32A32\TC\LIB\PIO.C → library source file
- ...\P32C32P32A32\TC\LIB\TCLIB.BAT → batch compiler file
- ...\P32C32P32A32\TC\LIB\TCPIO_L.LIB → I/O port large mode
- ...\P32C32P32A32\TC\LIB\TCPIO_H.LIB → I/O port huge mode
- ...\P32C32P32A32\TC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\P32C32P32A32\TC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\P32C32P32A32\TC\DEMO\PIO.H → library header file
- ...\P32C32P32A32\TC\DEMO\DEMO1.C → demo1 source file
- ...\P32C32P32A32\TC\DEMO\DEMO2.C → demo2 source file
- ...\P32C32P32A32\TC\DEMO\DEMO3.C → demo3 source file
- ...\P32C32P32A32\TC\DEMO\DEMO1.PRJ → TC project1 file
- ...\P32C32P32A32\TC\DEMO\DEMO2.PRJ → TC project2 file
- ...\P32C32P32A32\TC\DEMO\DEMO3.PRJ → TC project3 file
- ...\P32C32P32A32\TC\DEMO\DEMO1.EXE → demo1 execution file
- ...\P32C32P32A32\TC\DEMO\DEMO2.EXE → demo2 execution file
- ...\P32C32P32A32\TC\DEMO\DEMO3.EXE → demo3 execution file

- ...\P32C32P32A32\TC\DIAG\PIO.H → library header file
- ...\P32C32P32A32\TC\DIAG\PIO_PISO.C → I/O source code
- ...\P32C32P32A32\TC\DIAG\PIO_PISO.PRJ → TC project file
- ...\P32C32P32A32\TC\DIAG\PIO_PISO.EXE → I/O execution file

- ...\P32C32P32A32\BC\LIB>*.* → for library source code
- ...\P32C32P32A32\BC\DEMO>*.* → demo program source code
- ...\P32C32P32A32\BC\DIAG>*.* → pio_piso auto detect program

- ...\P32C32P32A32\BC\LIB\PIO.H → library header file
- ...\P32C32P32A32\BC\LIB\PIO.C → library source file
- ...\P32C32P32A32\BC\LIB\BCLIB.BAT → batch compiler file
- ...\P32C32P32A32\BC\LIB\BCPIO_L.LIB → I/O port large mode
- ...\P32C32P32A32\BC\LIB\BCPIO_H.LIB → I/O port huge mode
- ...\P32C32P32A32\BC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\P32C32P32A32\BC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\P32C32P32A32\BC\DEMO\PIO.H → library header file
- ...\P32C32P32A32\BC\DEMO\DEMO1.C → demo1 source file
- ...\P32C32P32A32\BC\DEMO\DEMO2.C → demo2 source file
- ...\P32C32P32A32\BC\DEMO\DEMO3.C → demo3 source file
- ...\P32C32P32A32\BC\DEMO\DEMO1.PRJ → BC project1 file
- ...\P32C32P32A32\BC\DEMO\DEMO2.PRJ → BC project2 file
- ...\P32C32P32A32\BC\DEMO\DEMO3.PRJ → BC project3 file
- ...\P32C32P32A32\BC\DEMO\DEMO1.EXE → demo1 execution file
- ...\P32C32P32A32\BC\DEMO\DEMO2.EXE → demo2.execution file
- ...\P32C32P32A32\BC\DEMO\DEMO3.EXE → demo3 execution file

- ...\P32C32P32A32\BC\DIAG\PIO.H → library header file
- ...\P32C32P32A32\BC\DIAG\PIO_PISO.C → I/O source code
- ...\P32C32P32A32\BC\DIAG\PIO_PISO.PRJ → TC project file
- ...\P32C32P32A32\BC\DIAG\PIO_PISO.EXE → I/O execution file

- ...\P32C32P32A32\MSC\LIB>*.* → for library source code
- ...\P32C32P32A32\MSC\DEMO>*.* → demo program source code
- ...\P32C32P32A32\MSC\DIAG>*.* → pio_piso auto detect program

- ...\P32C32P32A32\MSC\LIB\PIO.H → library header file
- ...\P32C32P32A32\MSC\LIB\PIO.C → library source file
- ...\P32C32P32A32\MSC\LIB\MSCLIB.BAT → batch compiler file
- ...\P32C32P32A32\MSC\LIB\MSCPIO_L.LIB → I/O port large mode
- ...\P32C32P32A32\MSC\LIB\MSCPIO_H.LIB → I/O port huge mode
- ...\P32C32 P32A32\MSC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\P32C32 P32A32\MSC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\P32C32P32A32\MSC\DEMO\PIO.H → library header file
- ...\P32C32P32A32\MSC\DEMO\DEMO1.C → demo1 source file
- ...\P32C32P32A32\MSC\DEMO\DEMO2.C → demo2 source file
- ...\P32C32P32A32\MSC\DEMO\DEMO3.C → demo3 source file
- ...\P32C32P32A32\MSC\DEMO\MAKE1.BAT → demo1 batch file
- ...\P32C32P32A32\MSC\DEMO\MAKE2.BAT → demo2 batch file
- ...\P32C32P32A32\MSC\DEMO\MAKE3.BAT → demo3 batch file
- ...\P32C32P32A32\MSC\DEMO\DEMO1.EXE → demo1 execution file
- ...\P32C32P32A32\MSC\DEMO\DEMO2.EXE → demo2 execution file
- ...\P32C32P32A32\MSC\DEMO\DEMO3.EXE → demo3 execution file

- ...\P32C32P32A32\MSC\DIAG\PIO.H → library header file
- ...\P32C32P32A32\MSC\DIAG\PIO_PSIO.C → I/O source code
- ...\P32C32P32A32\MSC\DIAG\PIO.BAT → batch file
- ...\P32C32P32A32\MSC\DIAG\PIO_PISO.EXE → I/O execution file

:
:
:

5.2 Program file for PISO-P64

- ...\P64\TC>*.* → for Turbo C 2.xx or above
- ...\P64\BC>*.* → for Borland C++ 3.X above
- ...\P64\MSC>*.* → for Microsoft C 5.X above

- ...\P64\TC\LIB>*.* → for library source code
- ...\P64\TC\DEMO>*.* → demo program source code
- ...\P64\TC\DIAG>*.* → pio_piso auto detect program

- ...\P64\TC\LIB\PIO.H → library header file
- ...\P64\TC\LIB\PIO.C → library source file
- ...\P64\TC\LIB\TCLIB.BAT → batch compiler file
- ...\P64\TC\LIB\TCPIO_L.LIB → I/O port large mode
- ...\P64\TC\LIB\TCPIO_H.LIB → I/O port huge mode
- ...\P64\TC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\P64\TC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\P64\TC\DEMO\PIO.H → library header file
- ...\P64\TC\DEMO\DEMO1.C → demo1 source file
- ...\P64\TC\DEMO\DEMO1.PRJ → TC project1 file
- ...\P64\TC\DEMO\DEMO1.EXE → demo1 execution file

- ...\P64\TC\DIAG\PIO.H → library header file
- ...\P64\TC\DIAG\PIO_PISO.C → I/O source code
- ...\P64\TC\DIAG\PIO_PISO.PRJ → TC project file
- ...\P64\TC\DIAG\PIO_PISO.EXE → I/O execution file

- ...\P64\BC\LIB>*.* → for library source code
- ...\P64\BC\DEMO>*.* → demo program source code
- ...\P64\BC\DIAG>*.* → pio_piso auto detect program

- ...\P64\BC\LIB\PIO.H → library header file
- ...\P64\BC\LIB\PIO.C → library source file
- ...\P64\BC\LIB\BCLIB.BAT → batch compiler file
- ...\P64\BC\LIB\BCPIO_L.LIB → I/O port large mode
- ...\P64\BC\LIB\BCPIO_H.LIB → I/O port huge mode

- ...\P64\BC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\P64\BC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\P64\BC\DEMO\PIO.H → library header file
- ...\P64\BC\DEMO\DEMO1.C → demo1 source file
- ...\P64\BC\DEMO\DEMO1.PRJ → BC project1 file
- ...\P64\BC\DEMO\DEMO1.EXE → demo1 execution file

- ...\P64\BC\DIAG\PIO.H → library header file
- ...\P64\BC\DIAG\PIO_PISO.C → I/O source code
- ...\P64\BC\DIAG\PIO_PISO.PRJ → BC project file
- ...\P64\BC\DIAG\PIO_PISO.EXE → I/O execution file

- ...\P64\MSC\LIB>*.* → for library source code
- ...\P64\MSC\DEMO>*.* → demo program source code
- ...\P64\MSC\DIAG>*.* → pio_piso auto detect program

- ...\P64\MSC\LIB\PIO.H → library header file
- ...\P64\MSC\LIB\PIO.C → library source file
- ...\P64\MSC\LIB\MSCLIB.BAT → batch compiler file
- ...\P64\MSC\LIB\MSCPIO_L.LIB → I/O port large mode
- ...\P64\MSC\LIB\MSCPIO_H.LIB → I/O port huge mode
- ...\P64\MSC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\P64\MSC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\P64\MSC\DEMO\PIO.H → library header file
- ...\P64\MSC\DEMO\DEMO1.C → demo1 source file
- ...\P64\MSC\DEMO\MAKE1.BAT → demo1 batch file
- ...\P64\MSC\DEMO\DEMO1.EXE → demo1 execution file
-
- ...\P64\MSC\DIAG\PIO.H → library header file
- ...\P64\MSC\DIAG\PIO_PSIO.C → I/O source code
- ...\P64\MSC\DIAG\PIO.BAT → batch file
- ...\P64\MSC\DIAG\PIO_PISO.EXE → I/O execution file

5.3 Program file list for PISO-C64

- ...\C64A64\TC>*.* → for Turbo C 2.xx or above
- ...\C64A64\BC>*.* → for Borland C++ 3.X above
- ...\C64A64\MSC>*.* → for Microsoft C 5.X above

- ...\C64A64\TC\LIB>*.* → for library source code
- ...\C64A64\TC\DEMO>*.* → demo program source code
- ...\C64A64\TC\DIAG>*.* → pio_piso auto detect program

- ...\C64A64\TC\LIB\PIO.H → library header file
- ...\C64A64\TC\LIB\PIO.C → library source file
- ...\C64A64\TC\LIB\TCLIB.BAT → batch compiler file
- ...\C64A64\TC\LIB\TCPIO_L.LIB → I/O port large mode
- ...\C64A64\TC\LIB\TCPIO_H.LIB → I/O port huge mode
- ...\C64A64\TC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\C64A64\TC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\C64A64\TC\DEMO\PIO.H → library header file
- ...\C64A64\TC\DEMO\DEMO1.C → demo1 source file
- ...\C64A64\TC\DEMO\DEMO1.PRJ → TC project1 file
- ...\C64A64\TC\DEMO\DEMO1.EXE → demo1 execution file

- ...\C64A64\TC\DIAG\PIO.H → library header file
- ...\C64A64\TC\DIAG\PIO_PISO.C → I/O source code
- ...\C64A64\TC\DIAG\PIO_PISO.PRJ → I/O project file
- ...\C64A64\TC\DIAG\PIO_PISO.EXE → I/O execution file

- ...\C64A64\BC\LIB>*.* → for library source code
- ...\C64A64\BC\DEMO>*.* → demo program source code
- ...\C64A64\BC\DIAG>*.* → pio_piso auto detect program

- ...\C64A64\BC\LIB\PIO.H → library header file
- ...\C64A64\BC\LIB\PIO.C → library source file
- ...\C64A64\BC\LIB\BCLIB.BAT → batch compiler file
- ...\C64A64\BC\LIB\BCPIO_L.LIB → I/O port large mode
- ...\C64A64\BC\LIB\BCPIO_H.LIB → I/O port huge mode

- ...\C64A64\BC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\C64A64\BC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\C64A64\BC\DEMO\PIO.H → library header file
- ...\C64A64\BC\DEMO\DEMO1.C → demo1 source file
- ...\C64A64\BC\DEMO\DEMO1.PRJ → BC project1 file
- ...\C64A64\BC\DEMO\DEMO1.EXE → demo1 execution file
-
- ...\C64A64\BC\DIAG\PIO.H → library header file
- ...\C64A64\BC\DIAG\PIO_PISO.C → I/O source code
- ...\C64A64\BC\DIAG\PIO_PISO.PRJ → BC project file
- ...\C64A64\BC\DIAG\PIO_PISO.EXE → I/O execution file

- ...\C64A64\MSC\LIB>*.* → for library source code
- ...\C64A64\MSC\DEMO>*.* → demo program source code
- ...\C64A64\MSC\DIAG>*.* → pio_piso auto detect program

- ...\C64A64\MSC\LIB\PIO.H → library header file
- ...\C64A64\MSC\LIB\PIO.C → library source file
- ...\C64A64\MSC\LIB\MSCLIB.BAT → batch compiler file
- ...\C64A64\MSC\LIB\MSCPIO_L.LIB → I/O port large mode
- ...\C64A64\MSC\LIB\MSCPIO_H.LIB → I/O port huge mode
- ...\C64A64\MSC\LIB\IOPORT_L.LIB → I/O port large mode
- ...\C64A64\MSC\LIB\IOPORT_H.LIB → I/O port huge mode

- ...\C64A64\MSC\DEMO\PIO.H → library header file
- ...\C64A64\MSC\DEMO\DEMO1.C → demo1 source file
- ...\C64A64\MSC\DEMO\MAKE1.BAT → demo1 batch file
- ...\C64A64\MSC\DEMO\DEMO1.EXE → demo1 execution file

- ...\C64A64\MSC\DIAG\PIO.H → library header file
- ...\C64A64\MSC\DIAG\PIO_PISO.C → I/O source code
- ...\C64A64\MSC\DIAG\MAKE1.BAT → batch file
- ...\C64A64\MSC\DIAG\PIO_PISO.EXE → I/O execution file

5.4 Diagnostic program

5.4.1 Diagnostic program for DOS

```
/* ------------------------------------------------------------------------ */
/* Find all PIO_PISO series cards in this PC system          */
/* Step 1: plug all PIO_PISO cards into PC                  */
/* Step 2: run PIO_PISO.EXE                                 */
/* ------------------------------------------------------------------------ */

#include "PIO.H"

WORD wBase,wIrq;
WORD wBase2,wIrq2;

int main()
{
int  i,j,j1,j2,j3,j4,k,jj,dd,j11,j22,j33,j44;
WORD wBoards,wRetVal;
WORD wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice;
char c;
float ok,err;

clrscr();
wRetVal=PIO_DriverInit(&wBoards,0xff,0xff,0xff);  /*for PIO-PISO*/
printf("\nThrer are %d PIO_PISO Cards in this PC",wBoards);
if (wBoards==0 ) exit(0);

printf("\n-----------------------------------------------------");
for(i=0; i<wBoards; i++)
  {
  PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&wSubVendor,
          &wSubDevice,&wSubAux,&wSlotBus,&wSlotDevice);

  printf("\nCard_%d:wBase=%x,wIrq=%x,subID=[%x,%x,%x],
          SlotID=[%x,%x]",i,wBase,wIrq,wSubVendor,wSubDevice,
          wSubAux,wSlotBus,wSlotDevice);
  printf(" --> ");
  ShowPioPiso(wSubVendor,wSubDevice,wSubAux);
  }

PIO_DriverClose();
}
```

NOTE**: the PIO_PISO.EXE file is valid for all PIO/PISO cards**. Execute PIO_PISO.EXE to get the following information:

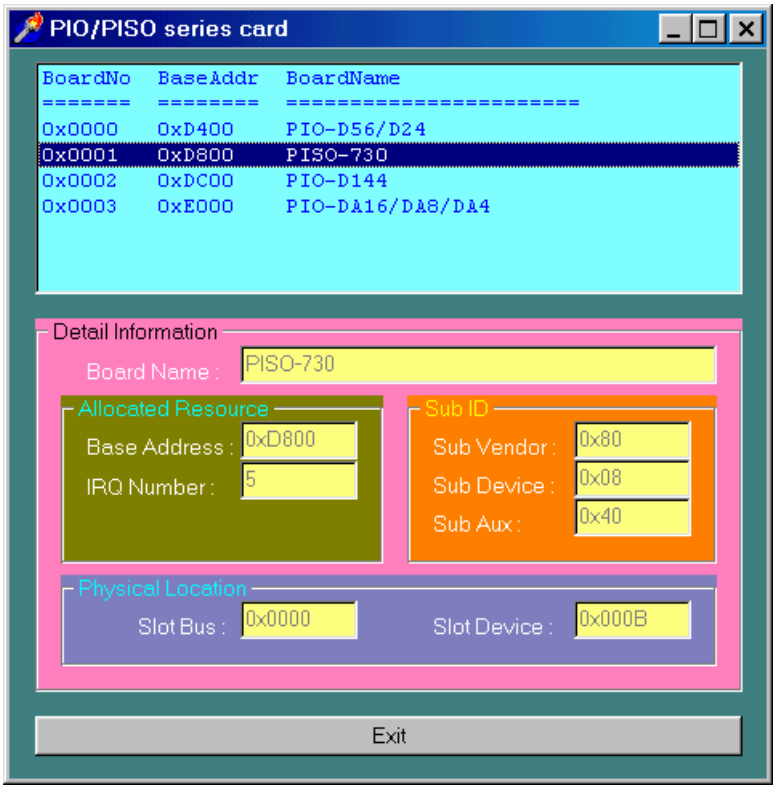
- A list all of PIO/PISO cards installed in this PC
- A list all of resources allocated to every PIO/PISO cards
- A list of wSlotBus & wSlotDevice for specified PIO/PISO card identification.

5.4.2 Diagnostic program for WINDOWS

The software utility “PIO_PISO.EXE” is designed for Windows 95/98/NT. For more detailed information about this file, please refer to the “Readme.txt” in Windows 95/98/NT development toolkit. It is useful for all PIO/PISO series cards.

- Follow these steps to setup the toolkit:
  Step 1: Toolkit (Softwares)/Manuals
  Step 2: I AGREE
  Step 3: PCI Bus DAQ Card
  Step 4: PIO_PISO
  Step 5: Install Toolkits for WINDOWS 98/98 or NT

After executing the utility, all detail information for all PIO/PISO cards that have been installed in the PC will be shown as follows:



5.5 Demo program for PISO-P32C32/P32A32

5.5.1 DEMO1 for PISO-P32C32/P32A32

```
/* ---------------------------------------------------------------------------*/
/* Demo 1: Digital Output of PISO-P32C32/P32A32                               */
/* Step 1: The circuit diagram of hardware: refer to Sec 4.1                  */
/* Step 2: run demo1.EXE                                                      */
/* ---------------------------------------------------------------------------*/

#include <dos.h>
#include "PIO.H"

int main()
{
char c;
BYTE i;
WORD wBoards,wRetVal;
WORD wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice;

clrscr();
wRetVal=PIO_DriverInit(&wBoards,0x80,0x08,0x20);/*for PISO-P32C32*/
                                        0x80,0x08,0x70);/*for PISO-P32A32*/

printf("\n(1) Threr are %d PISO-P32C32 Cards in this PC",wBoards);
if ( wBoards==0 )
  {
  putch(0x07);  putch(0x07);  putch(0x07);
  printf("\n(1) There are no PISO-P32C32 card in this PC !!!");
  exit(0);
  }

printf("\n(2) The Configuration Space ->   wBase");

for(i=0; i<wBoards; i++)
  {
   PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&wSubVendor,&wSubDevice,&wSubAux,
                        &wSlotBus,&wSlotDevice);
   printf("\nCard_%d: wBase=%x,wIrq=%x,subID=[%x,%x,%x],SlotID=[%x,%x]"
         ,i,wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice);
  }
```

```
/* step 1: enable all D/I/O port                */
outportb(wBase,1);              /* enable D/I/O */

/* step 2: Digital output from DO_0 to DO_31    */
while(1)
{
printf("\n\n --------- Digital output of PISO-P32C32  ----------");
for (i=1;i<=0x80;i=i<<1)
   {
     outportb(wBase+0xc0,i);      /* DO_07 to DO_00 */
     outportb(wBase+0xc4,i);      /* DO_15 to DO_08 */
     outportb(wBase+0xc8,i);      /* DO_23 to DO_16 */
     outportb(wBase+0xcc,i);      /* DO_31 to DO_24 */



     printf("\nD 31-0 Output Value = %02x,%02x,%02x,%02x",i,i,i,i);
     sleep(1);

 if(i==0x80)  { i=0x01; break; }

   if (kbhit()!=0)
     {
     c=getch();
     if ((c=='q') || (c=='Q') ||  c==27 )
     return;
     }
   delay(1);
   }  /* end of while */
 }   /* end of for */

 PIO_DriverClose();

}
```

5.5.2 DEMO2 for PISO-P32C32/P32A32

```
/*---------------------------------------------------------------------------*/
/* Demo 2: Digital input of PISO-P32C32/P32A32                               */
/* Step 1: The circuit diagram of hardware: refer to Sec 4.1                 */
/* Step 2: run demo2.EXE                                                     */
/* ------------------------------------------------------------------------- */

#include <dos.h>
#include "PIO.H"

int main()
{
WORD wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice;
BYTE i,j1,j2,j3,j4;
char c;

WORD wBoards,wRetVal;

clrscr();
wRetVal=PIO_DriverInit(&wBoards,0x80,0x08,0x20); /* for PISO-P32C32*/
                                        0x80,0x08,0x70); /* for PISO-P32A32*/

printf("\n(1) Threr are %d PISO-P32C32 Cards in this PC",wBoards);
if ( wBoards==0 )
  {
  putch(0x07);  putch(0x07);  putch(0x07);
  printf("\n(1) There are no PISO-P32C32 card in this PC !!!");
  exit(0);
  }

printf("\n(2) The Configuration Space ->   wBase");

for(i=0; i<wBoards; i++)
  {
   PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&wSubVendor,&wSubDevice,&wSubAux,
                        &wSlotBus,&wSlotDevice);
   printf("\nCard_%d: wBase=%x,wIrq=%x,subID=[%x,%x,%x],SlotID=[%x,%x]"
         ,i,wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice);
  }

/* step 1: enable all D/I/O port                */
outportb(wBase,1);              /* enable D/I/O */
```

```
/* step 2: digital input from DI_0 to DI_31          */
while(1)
{
  for ( ; ; )
    {
  printf("\n\n --------- Digital input of PISO-P32C32 ------------");
      j1=inportb(wBase+0xc0)^0xff;   /* DI_07 to DI_00 */
      j2=inportb(wBase+0xc4)^0xff;   /* DI_15 to DI_08 */
      j3=inportb(wBase+0xc8)^0xff;   /* DI_23 to DI_16 */
      j4=inportb(wBase+0xcc)^0xff;   /* DI_31 to DI_24 */

      printf("\nD 31-0 Input  Value = %02x,%02x,%02x,%02x",j4,j3,j2,j1);
      sleep(1);

 if(i==0x80)  { i=0x01; break; }

    if (kbhit()!=0)
       {
       c=getch();
       if ((c=='q') || (c=='Q') ||  c==27 )
       return;
       }
    delay(1);
    }  /* end of while */
  } /* end of for */

 PIO_DriverClose();

}
```

5.5.3 DEMO3 for PISO-P32C32/P32A32

```
/* ---------------------------------------------------------------------------- */
/* Demo 3: Digital I/O test of PISO-P32C32/P32A32                               */
/* Step 1: The circuit diagram of hardware: refer to Sec 4.1                    */
/* Step 2: run demo3.EXE                                                        */
/* ---------------------------------------------------------------------------- */

#include <dos.h>
#include "PIO.H"

int main()
{
WORD wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice;
BYTE i,j1,j2,j3,j4;
char c;

WORD wBoards,wRetVal;

clrscr();
wRetVal=PIO_DriverInit(&wBoards,0x80,0x08,0x20);/* for PISO-P32C32 */
                                        0x80,0x08,0x70);/* for PISO-P32A32 */
printf("\n(1) Threr are %d PISO-P32C32 Cards in this PC",wBoards);
if ( wBoards==0 )
  {
  putch(0x07);  putch(0x07);  putch(0x07);
  printf("\n(1) There are no PISO-P32C32 card in this PC !!!");
  exit(0);
  }

printf("\n(2) The Configuration Space ->   wBase");

for(i=0; i<wBoards; i++)
  {
   PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&wSubVendor,&wSubDevice,&wSubAux,
                        &wSlotBus,&wSlotDevice);
   printf("\nCard_%d: wBase=%x,wIrq=%x,subID=[%x,%x,%x],SlotID=[%x,%x]"
         ,i,wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice);
  }

/* step 1: enable all D/I/O port                    */
outportb(wBase,1);                    /* enable D/I/O */

/* step 2: DO_0 to DO_31 send to DI_0 to DI_31       */
while(1)
{
printf("\n\n --------- PISO-P32C32 test by itself ------------");
for (i=1;i<=0x80;i=i<<1)
   {

     outportb(wBase+0xc0,i);          /* DO_07 to DO_00 */
     outportb(wBase+0xc4,i);          /* DO_15 to DO_08 */
     outportb(wBase+0xc8,i);          /* DO_23 to DO_16 */
     outportb(wBase+0xcc,i);          /* DO_31 to DO_24 */
     delay(1);                      /* about to wait 1m sec */
     j1=inportb(wBase+0xc0)^0xff;      /* DI_07 to DI_00 */
     j2=inportb(wBase+0xc4)^0xff;      /* DI_15 to DI_08 */
     j3=inportb(wBase+0xc8)^0xff;      /* DI_23 to DI_16 */
     j4=inportb(wBase+0xcc)^0xff;      /* DI_31 to DI_24 */
```

```
 printf("\nD 31-0 Output Value = %02x,%02x,%02x,%02x",i,i,i,i);
 printf("\nD 31-0 Input  Value = %02x,%02x,%02x,%02x\n",j4,j3,j2,j1);

 if( i != j1 )
  {
   printf("\nD I/O 7-0 error in here!\n");
   putch(0x07);  putch(0x07);  putch(0x07);
  }
   if( i != j2 )
       {
        printf("\nD I/O 15-8  error in here!\n");
        putch(0x07);  putch(0x07);  putch(0x07);
       }
    if( i != j3 )
       {
        printf("\nD I/O 24-16 error in here!\n");
        putch(0x07);  putch(0x07);  putch(0x07);
       }
       if( i != j4 )
       {
        printf("\nD I/O 31-25 error in here!\n");
        putch(0x07);  putch(0x07);  putch(0x07);
       }

 if(i==j1 & i==j2 & i==j3 & i==j4)
 {
  printf("The Digital I/O test of PISO-P32C32 by itself OK!\n");
 }

 if(i==0x80)  { i=0x01; break; }

   if (kbhit()!=0)
      {
      c=getch();
      if ((c=='q') || (c=='Q') ||  c==27 )
      return;
      }
   delay(1);
   }  /* end of while */
 }  /* end of for */

 PIO_DriverClose();

}
```

5.6 Demo program for PISO-P64

5.6.1 DEMO1 for PISO-P64

```
/* ---------------------------------------------------------------------------- */
/* Demo 1: Digital Input of PISO-P64                                            */
/* Step 1: The circuit diagram of hardware: refer to Sec 4.2    */
/* Step 2: run demo1.EXE                                                        */
/* ---------------------------------------------------------------------------- */

#include <dos.h>
#include "PIO.H"


int main()
{
char c;
BYTE i,r1,r2,r3,r4,r5,r6,r7,r8;
WORD wBoards,wRetVal;
WORD wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice;

clrscr();
wRetVal=PIO_DriverInit(&wBoards,0x80,0x08,0x10);  /* for PISO-P64 */
printf("\n(1) Threr are %d PISO-P64 Cards in this PC",wBoards);
if ( wBoards==0 )
  {
  putch(0x07);  putch(0x07);  putch(0x07);
  printf("\n(1) There are no PISO-P64 card in this PC !!!");
  exit(0);
  }

printf("\n(2) The Configuration Space ->   wBase");

for(i=0; i<wBoards; i++)
  {
   PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&wSubVendor,&wSubDevice,&wSubAux,
                        &wSlotBus,&wSlotDevice);
   printf("\nCard_%d: wBase=%x,wIrq=%x,subID=[%x,%x,%x],SlotID=[%x,%x]"
         ,i,wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice);
  }

/* step 1: enable all D/I/O port                        */
outportb(wBase,1);              /* enable D/I/O */

/* step 2: Digital input from DI_0 to DI_63         */
while(1)
{

for ( ; ;)
   {
    printf("\n--------- Digital input of PISO-P64  ----------");
    r1 =inportb(wBase+0xc0);      /* DI_07 to DI_0  */
    r2 =inportb(wBase+0xc4);      /* DI_15 to DI_08 */
    r3 =inportb(wBase+0xc8);        /* DI_23 to DI_16 */
    r4 =inportb(wBase+0xcc);        /* DI_31 to DI_24 */

    r5 =inportb(wBase+0xd0);      /* DI_39 to DI_32 */
    r6 =inportb(wBase+0xd4);      /* DI_47 to DI_40 */
```

```
    r7 =inportb(wBase+0xd8);        /* DI_55 to DI_48 */
    r8 =inportb(wBase+0xdc);        /* DI_63 to DI_56 */

     printf("\nThe CON1 of PISO-P64 ...");
     printf("\nD31- 0 Input Value = %02x,%02x,%02x,%02x\n",r4,r3,r2,r1);

     printf("\nThe CON2 of PISO-P64 ...");
     printf("\nD63-32 Input Value = %02x,%02x,%02x,%02x\n",r8,r7,r6,r5);
     sleep(1);

   if (kbhit()!=0)
     {
     c=getch();
     if ((c=='q') || (c=='Q') ||  c==27 )
     return;
     }
   delay(1);
   }  /* end of while */
 }   /* end of for */

 PIO_DriverClose();

}
```

5.7 Demo program for PISO-C64/A64

5.7.1 DEMO1 for PISO-C64/A64

```
/* ---------------------------------------------------------------------------- */
/* Demo 1: Digital Output of PISO-C64                                           */
/* Step 1: The circuit diagram of hardware: refer to Sec 4.3                    */
/* Step 2: run demo1.EXE                                                        */
/* ---------------------------------------------------------------------------- */

#include <dos.h>
#include "PIO.H"

int main()
{
char c;
BYTE i;
WORD wBoards,wRetVal;
WORD wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice;

clrscr();
wRetVal=PIO_DriverInit(&wBoards,0x80,0x08,0x00);  /* for PISO-C64 */
                                  0x80,0x08,0x50);  /* for PISO-A64 */
printf("\n(1) Threr are %d PISO-C64 Cards in this PC",wBoards);
if ( wBoards==0 )
  {
  putch(0x07);  putch(0x07);  putch(0x07);
  printf("\n(1) There are no PISO-C64 card in this PC !!!");
  exit(0);
  }

printf("\n(2) The Configuration Space ->   wBase");

for(i=0; i<wBoards; i++)
  {
   PIO_GetConfigAddressSpace(i,&wBase,&wIrq,&wSubVendor,&wSubDevice,&wSubAux,
                    &wSlotBus,&wSlotDevice);
   printf("\nCard_%d: wBase=%x,wIrq=%x,subID=[%x,%x,%x],SlotID=[%x,%x]"
         ,i,wBase,wIrq,wSubVendor,wSubDevice,wSubAux,wSlotBus,wSlotDevice);
  }

/* step 1: enable all D/I/O port                    */
outportb(wBase,1);              /* enable D/I/O   */

/* step 2: Digital output from DO_0 to DO_63       */
while(1)
{
printf("\n\n --------- Digital output of PISO-C64  ----------");
for (i=1;i<=0x80;i=i<<1)
   {
     outportb(wBase+0xc0,i);       /* DO_07 to DO_00 */
     outportb(wBase+0xc4,i);       /* DO_15 to DO_08 */
     outportb(wBase+0xc8,i);          /* DO_23 to DO_16 */
     outportb(wBase+0xcc,i);          /* DO_31 to DO_24 */
     outportb(wBase+0xd0,i);       /* DO_39 to DO_32 */
     outportb(wBase+0xd4,i);       /* DO_47 to DO_40 */
     outportb(wBase+0xd8,i);          /* DO_55 to DO_48 */
```

```
      outportb(wBase+0xdc,i);           /* DO_63 to DO_56 */

      printf("\nThe CON1 of PISO-C64 ...");
      printf("\nD31- 0 Output Value = %02x,%02x,%02x,%02x\n",i,i,i,i);

      printf("\nThe CON2 of PISO-C64 ...");
      printf("\nD63-32 Output Value = %02x,%02x,%02x,%02x\n",i,i,i,i);
      sleep(1);

  if(i==0x80)  { i=0x01; break; }

     if (kbhit()!=0)
        {
        c=getch();
        if ((c=='q') || (c=='Q') ||  c==27 )
        return;
        }
     delay(1);
     }  /* end of while */
   }   /* end of for */

  PIO_DriverClose();

 }
```